

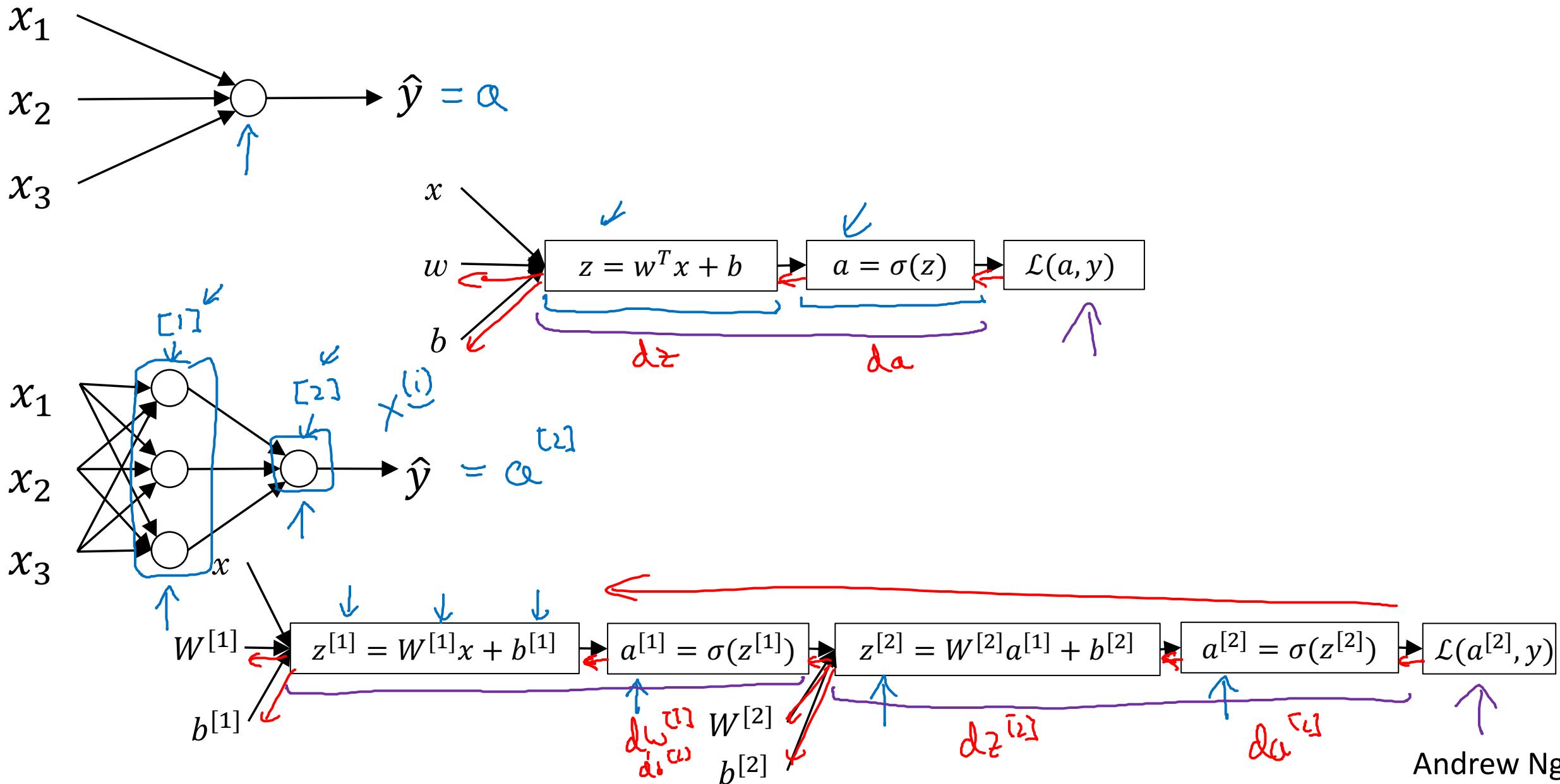


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One hidden layer
Neural Network

Neural Networks
Overview

What is a Neural Network?



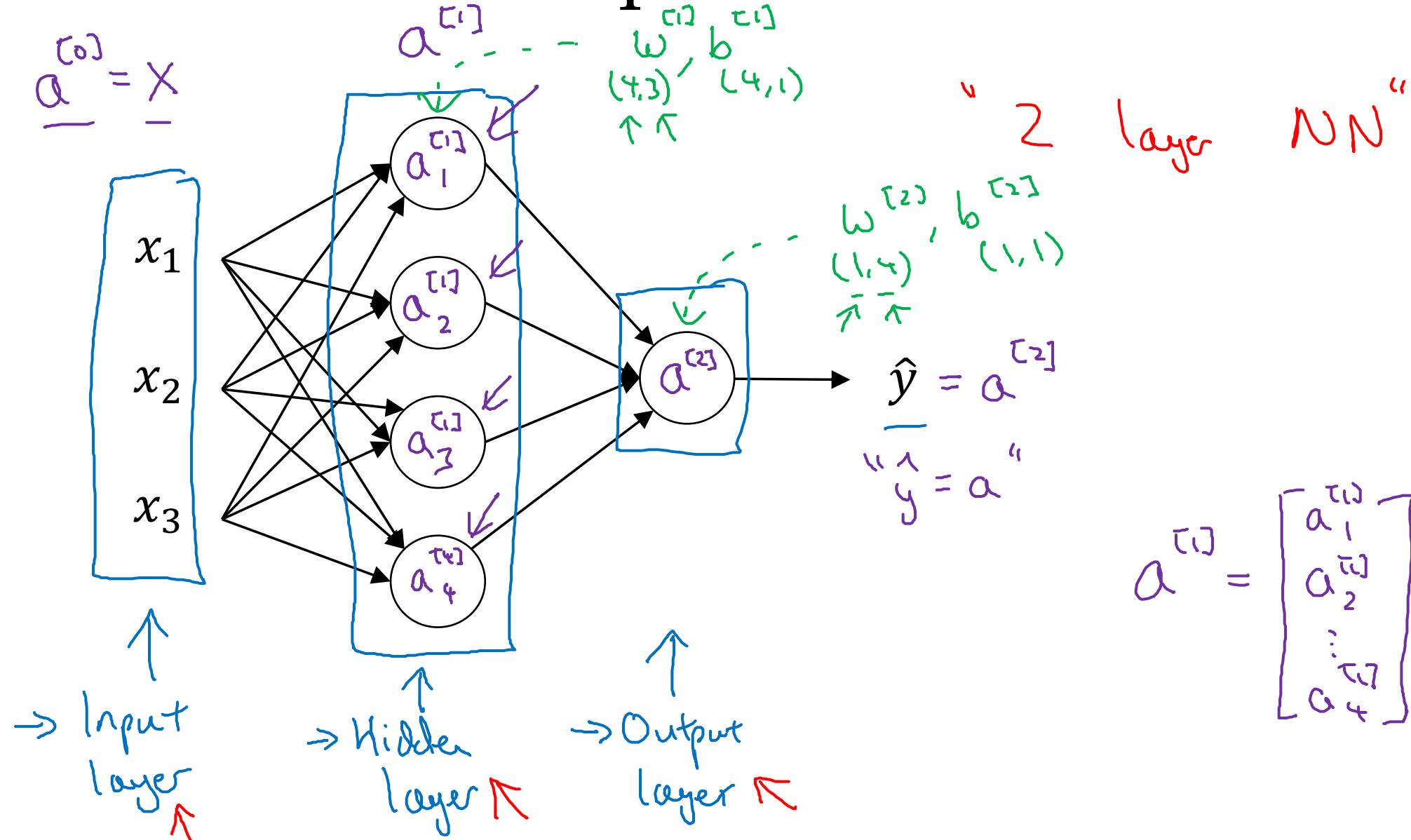


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One hidden layer
Neural Network

Neural Network
Representation

Neural Network Representation



$$a^{(1)} = \begin{bmatrix} a_1^{(1)} \\ a_2^{(1)} \\ \vdots \\ a_4^{(1)} \end{bmatrix}$$

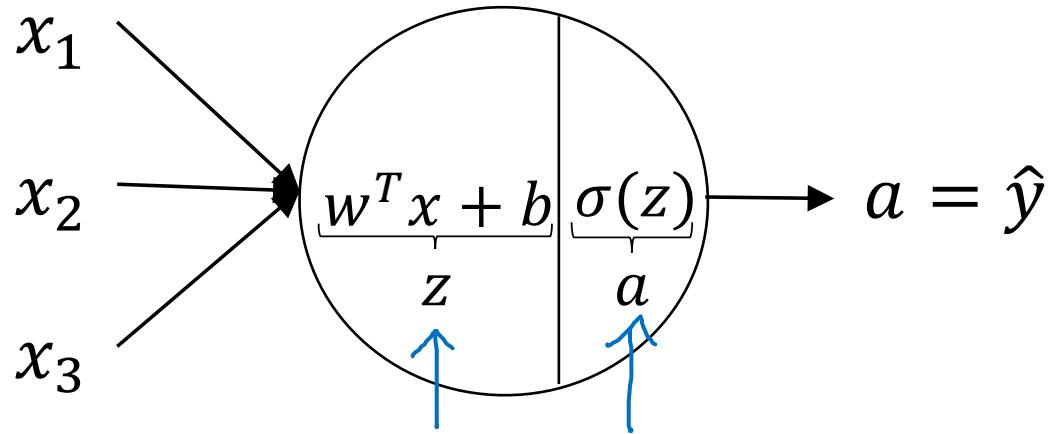


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One hidden layer Neural Network

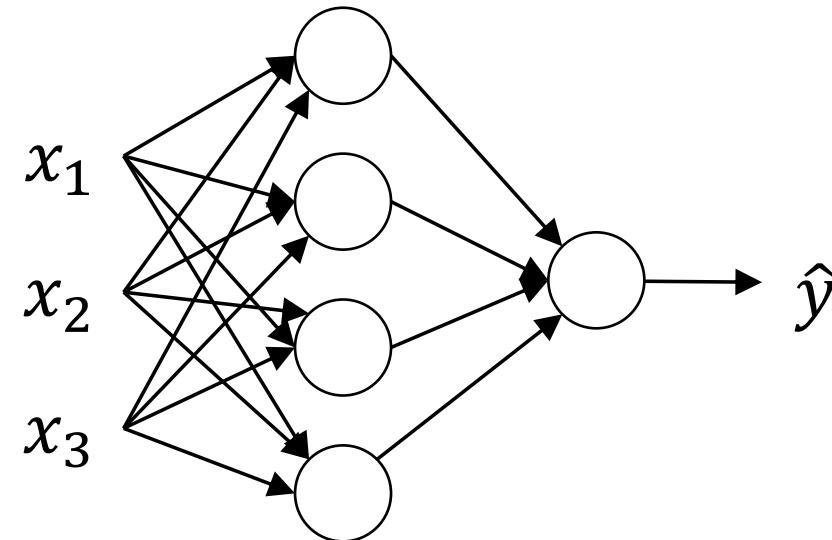
Computing a Neural Network's Output

Neural Network Representation

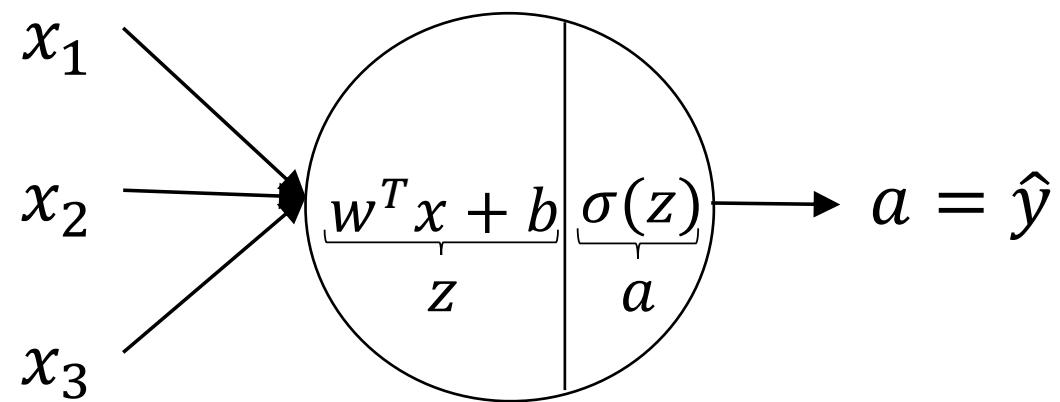


$$z = w^T x + b$$

$$a = \sigma(z)$$

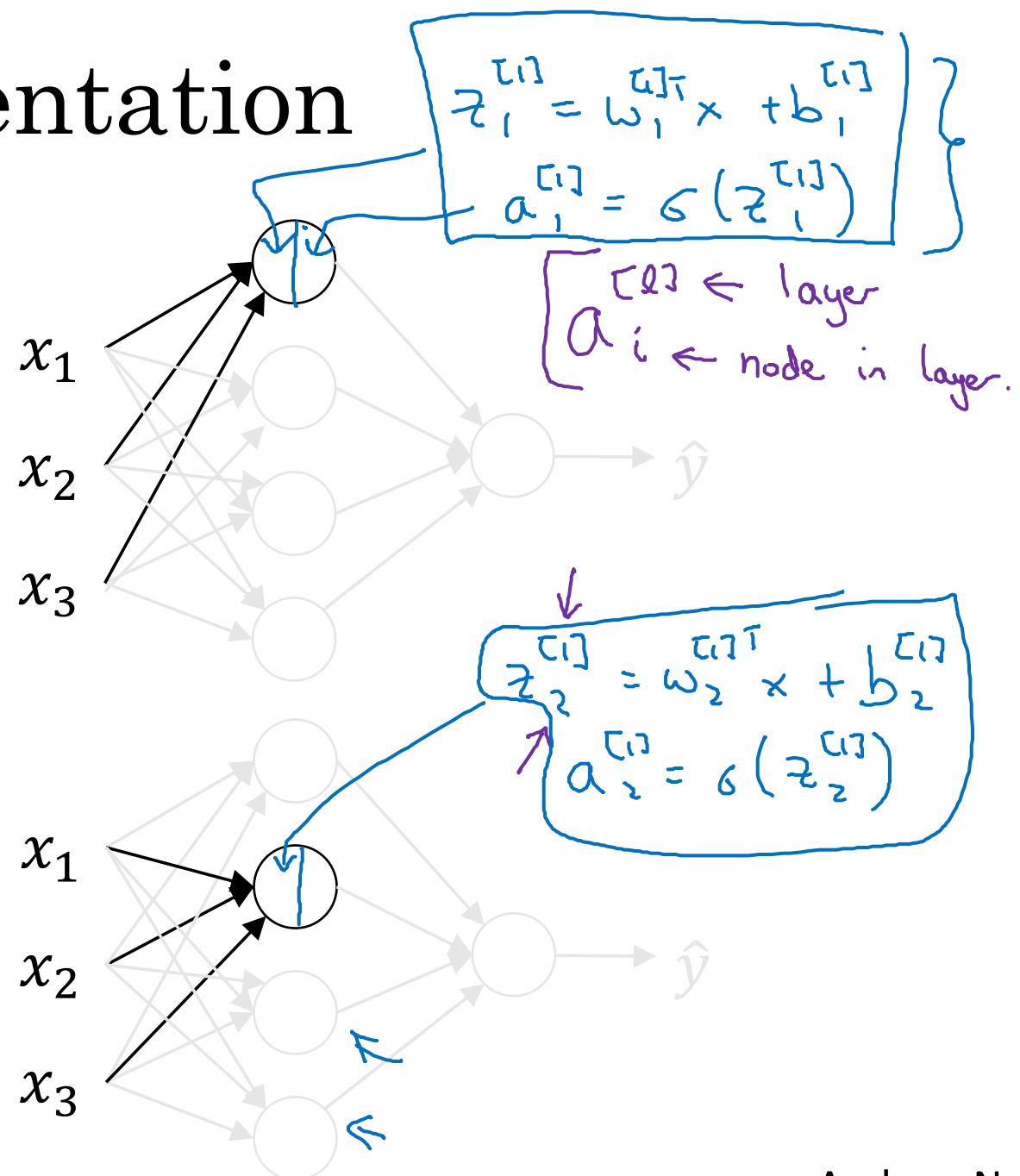


Neural Network Representation

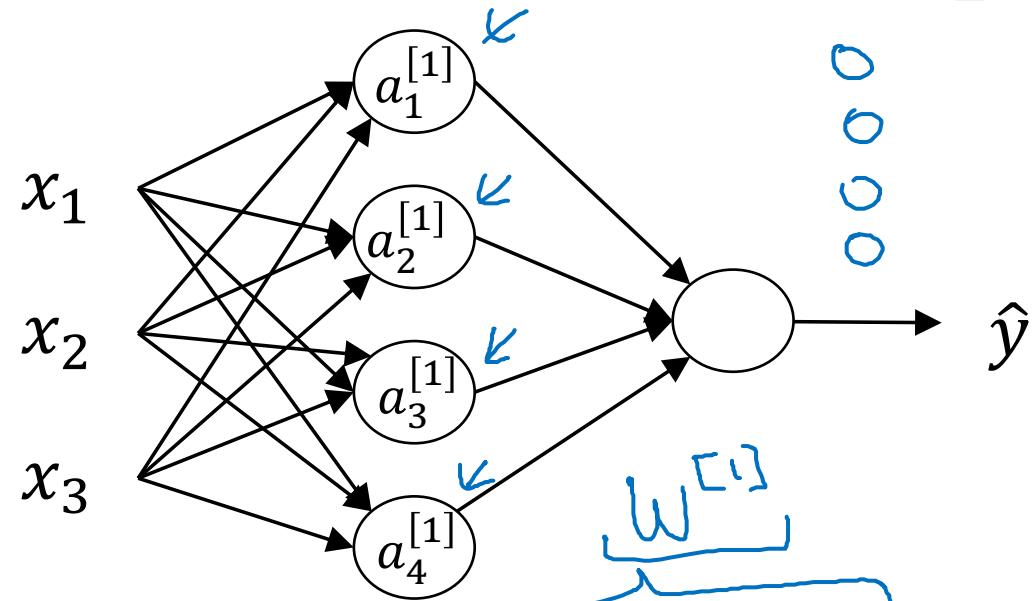


$$z = w^T x + b$$

$$a = \sigma(z)$$



Neural Network Representation



$$\rightarrow z^{[1]} = \begin{bmatrix} w_1^{[1]T} \\ w_2^{[1]T} \\ w_3^{[1]T} \\ w_4^{[1]T} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix}$$

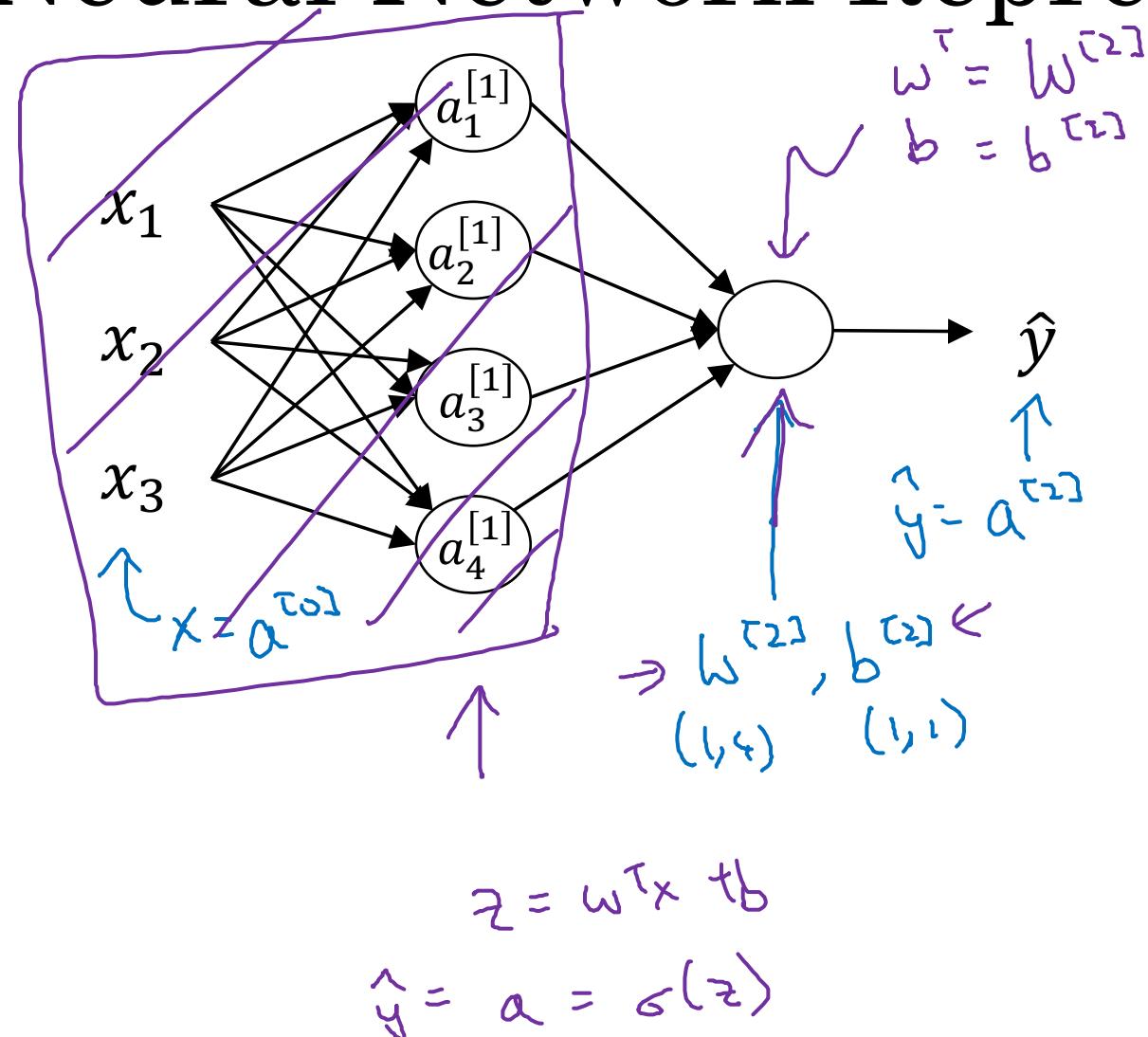
$$\rightarrow a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \\ a_3^{[1]} \\ a_4^{[1]} \end{bmatrix} = g(z^{[1]})$$

$(w_i^{[1]T} x)^{\top} a^{[1]}$

$z_1^{[1]} = w_1^{[1]T} x + b_1^{[1]}$	$a_1^{[1]} = \sigma(z_1^{[1]})$
$z_2^{[1]} = w_2^{[1]T} x + b_2^{[1]}$	$a_2^{[1]} = \sigma(z_2^{[1]})$
$z_3^{[1]} = w_3^{[1]T} x + b_3^{[1]}$	$a_3^{[1]} = \sigma(z_3^{[1]})$
$z_4^{[1]} = w_4^{[1]T} x + b_4^{[1]}$	$a_4^{[1]} = \sigma(z_4^{[1]})$

$$= \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix}$$

Neural Network Representation learning



Given input x :

$$\rightarrow z^{[1]} = W^{[1]} a^{[0]} + b^{[1]} \quad (4, 1) \quad (4, 3) \quad (3, 1) \quad (4, 1)$$

$$\rightarrow a^{[1]} = \sigma(z^{[1]}) \quad (4, 1) \quad (4, 1)$$

$$\rightarrow z^{[2]} = W^{[2]} a^{[1]} + b^{[2]} \quad (1, 1) \quad (1, 4) \quad (4, 1) \quad (1, 1)$$

$$\rightarrow a^{[2]} = \sigma(z^{[2]}) \quad (1, 1) \quad (1, 1)$$

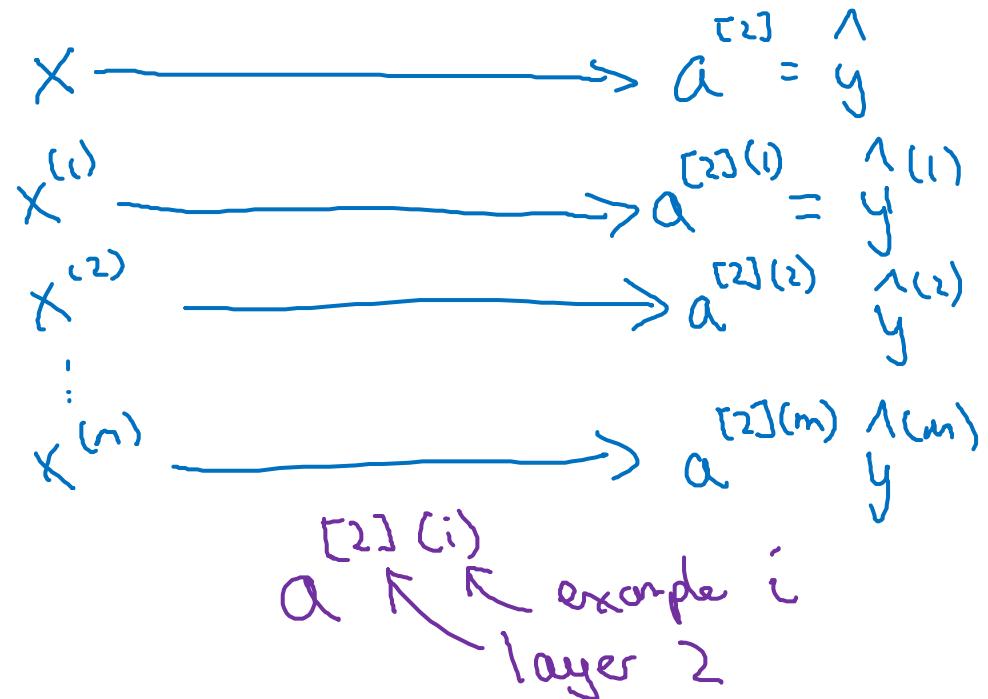
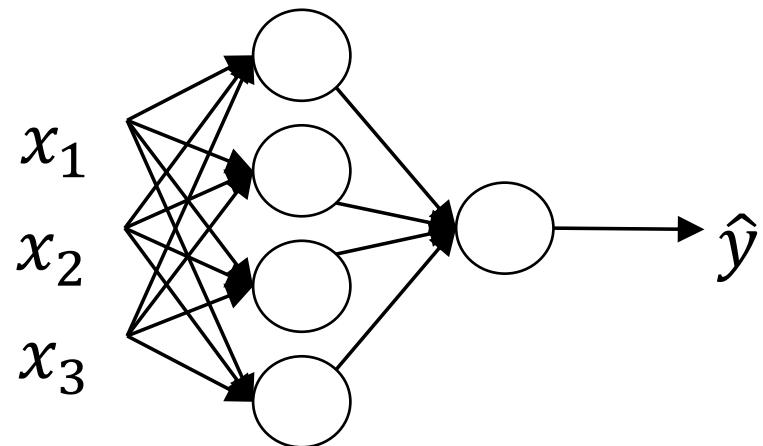


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One hidden layer Neural Network

Vectorizing across
multiple examples

Vectorizing across multiple examples



$\left. \begin{array}{l} z^{[1]} = W^{[1]}x + b^{[1]} \\ a^{[1]} = \sigma(z^{[1]}) \\ z^{[2]} = W^{[2]}a^{[1]} + b^{[2]} \\ a^{[2]} = \sigma(z^{[2]}) \end{array} \right\}$

for $i = 1$ to m ,

$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$

$a^{[1](i)} = \sigma(z^{[1](i)})$

$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$

$a^{[2](i)} = \sigma(z^{[2](i)})$

Vectorizing across multiple examples

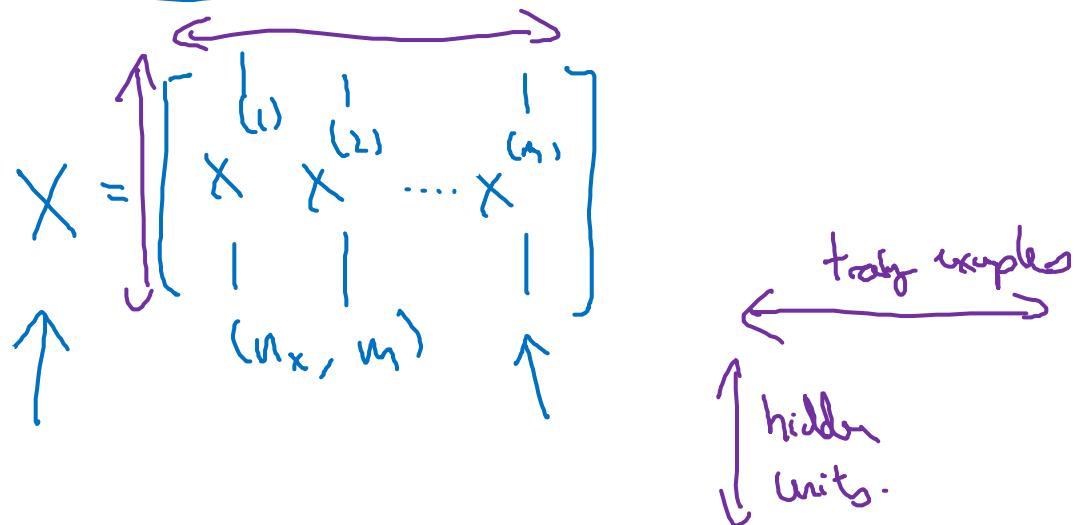
for $i = 1$ to m :

$$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$$

$$a^{[1](i)} = \sigma(z^{[1](i)})$$

$$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$$

$$a^{[2](i)} = \sigma(z^{[2](i)})$$

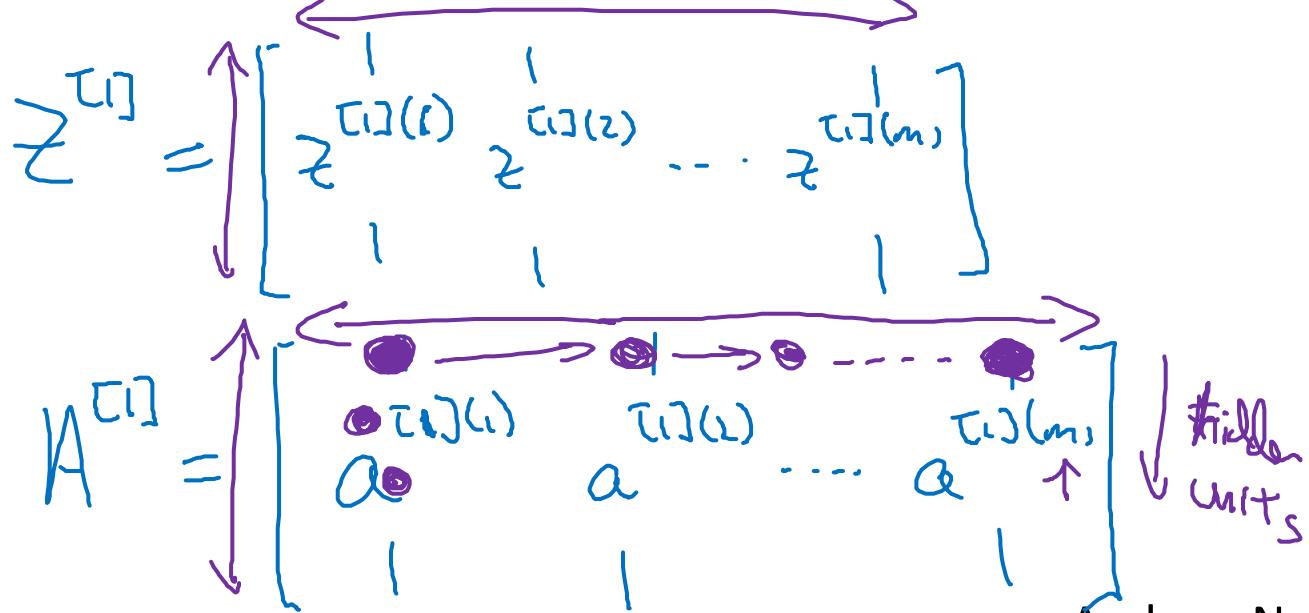


$$z^{[1]} = W^{[1]}X + b^{[1]}$$

$$\rightarrow A^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$\rightarrow A^{[2]} = \sigma(z^{[2]})$$





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One hidden layer
Neural Network

Explanation
for vectorized
implementation

Justification for vectorized implementation

$$z^{(1)(1)} = w^{(1)} x^{(1)} + b^{(1)}, \quad z^{(1)(2)} = w^{(1)} x^{(2)} + b^{(1)}, \quad z^{(1)(3)} = w^{(1)} x^{(3)} + b^{(1)}$$

$$w^{(1)} = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}$$

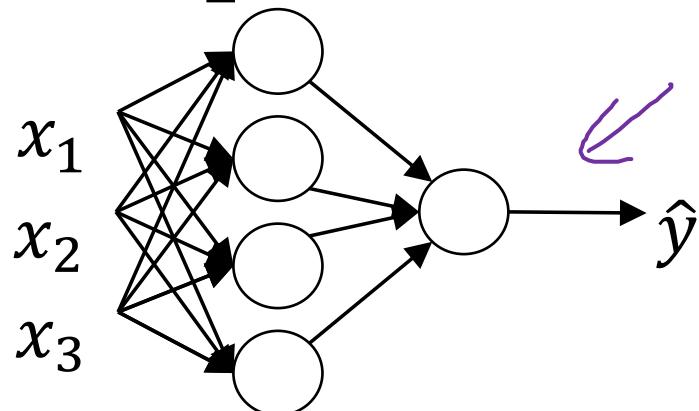
$$w^{(1)} x^{(1)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$w^{(1)} x^{(2)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$w^{(1)} x^{(3)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$\begin{aligned} z^{(1)} &= w^{(1)} X + b^{(1)} \\ &\quad \times \Sigma \\ &= \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} = \begin{bmatrix} z^{(1)(1)} \\ z^{(1)(2)} \\ z^{(1)(3)} \\ \vdots \end{bmatrix} = z^{(1)} \end{aligned}$$
$$w^{(1)} x^{(1)} = z^{(1)(1)}$$
$$+ b^{(1)}$$
$$+ b^{(1)}$$
$$+ b^{(1)}$$

Recap of vectorizing across multiple examples



$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | \end{bmatrix}$$

A vertical stack of input vectors $x^{(1)}, x^{(2)}, \dots, x^{(m)}$. A purple arrow points from the text "vectorizing across multiple examples" to this equation.

$$\underline{A^{[1]}} = \begin{bmatrix} | & | & | \\ a^{1} & a^{[1](2)} & \dots & a^{[1](m)} \\ | & | & | \end{bmatrix}$$

A vertical stack of hidden layer activations $a^{1}, a^{[1](2)}, \dots, a^{[1](m)}$. A purple arrow points from the text "vectorizing across multiple examples" to this equation.

```

for i = 1 to m
    z[1](i) = W[1]x(i) + b[1]
    → a[1](i) = σ(z[1](i))
    → z[2](i) = W[2]a[1](i) + b[2]
    → a[2](i) = σ(z[2](i))

```

Handwritten annotations: $x = a^{[1]}$ and $x^{(i)} = a^{[1](i)}$ are written next to the equations for $a^{[1]}$ and $a^{[2]}$ respectively.

```

Z[1] = W[1]X + b[1] ← wT,1A[1]+bT,1
A[1] = σ(Z[1])
Z[2] = W[2]A[1] + b[2]
A[2] = σ(Z[2])

```

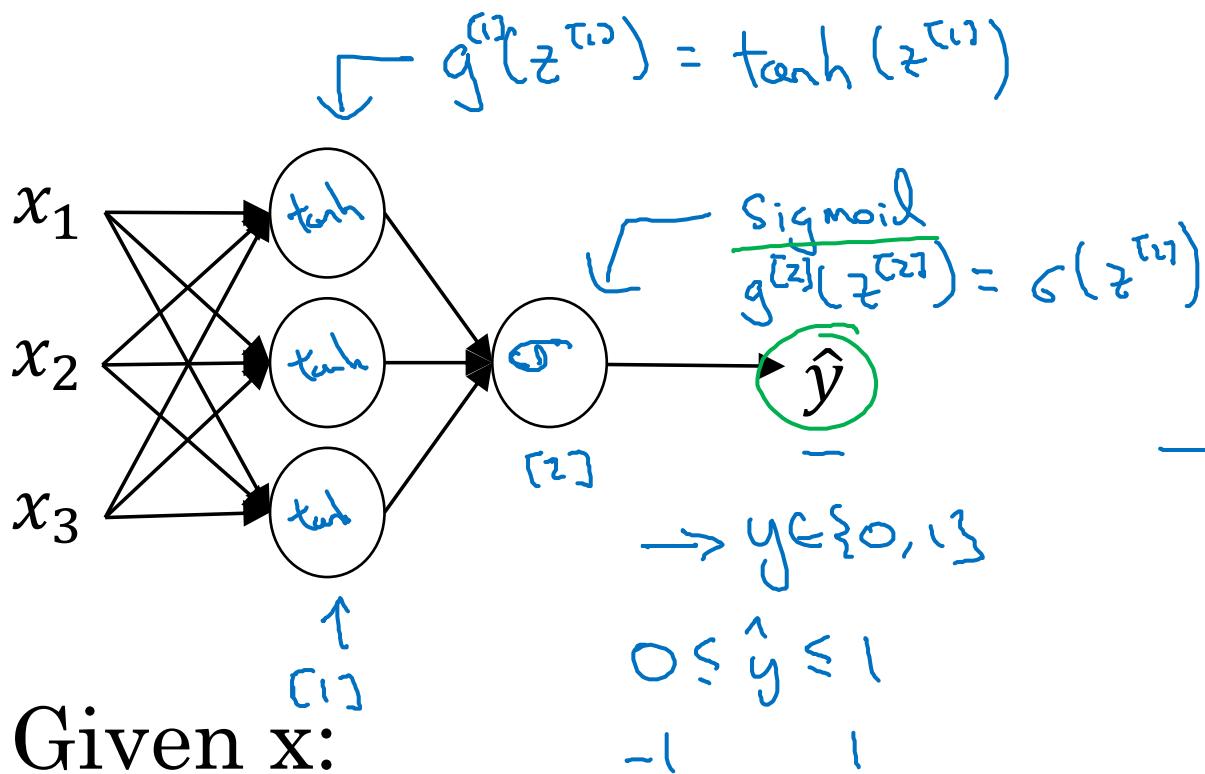


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One hidden layer Neural Network

Activation functions

Activation functions

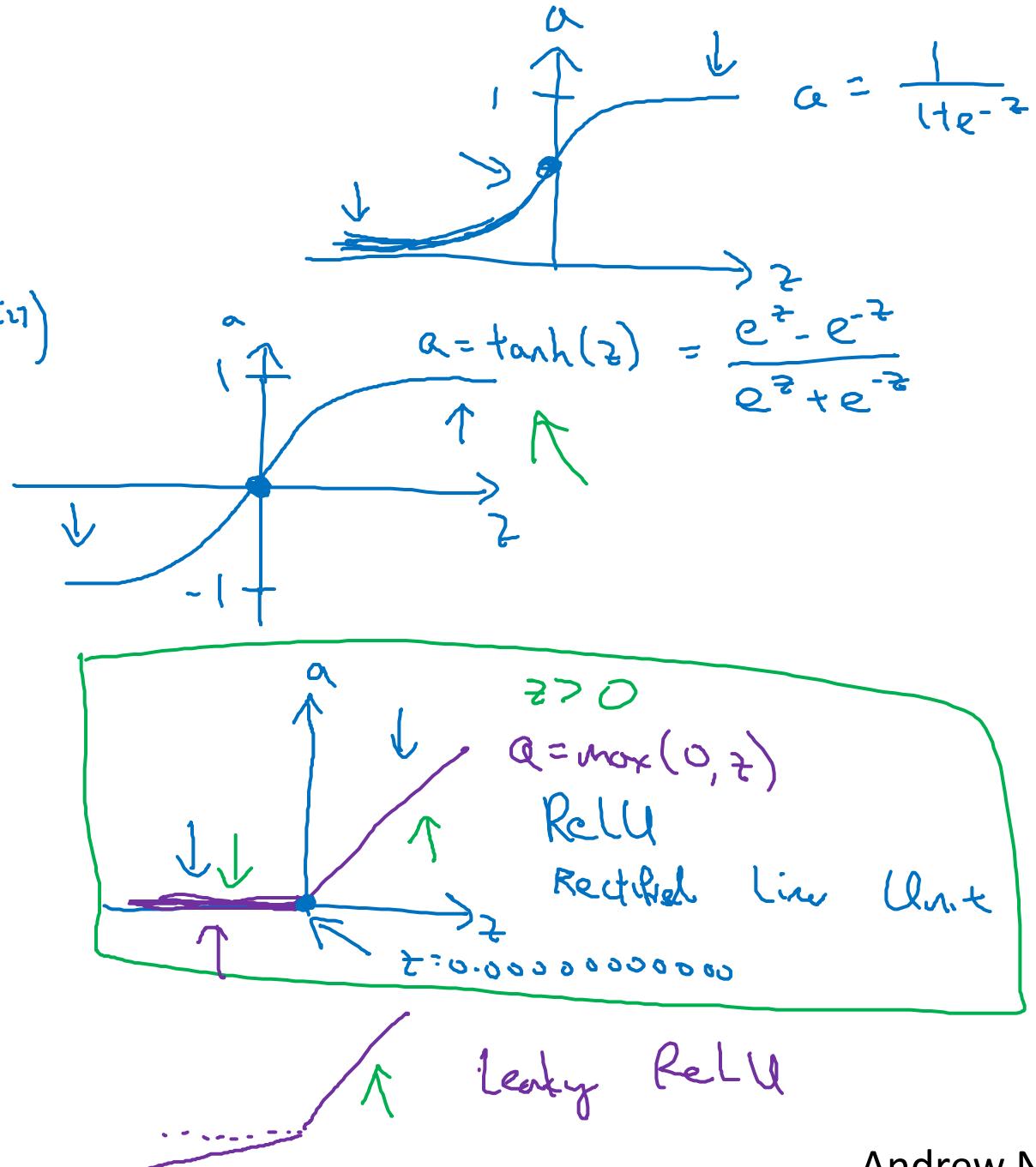


$$z^{[1]} = W^{[1]}x + b^{[1]}$$

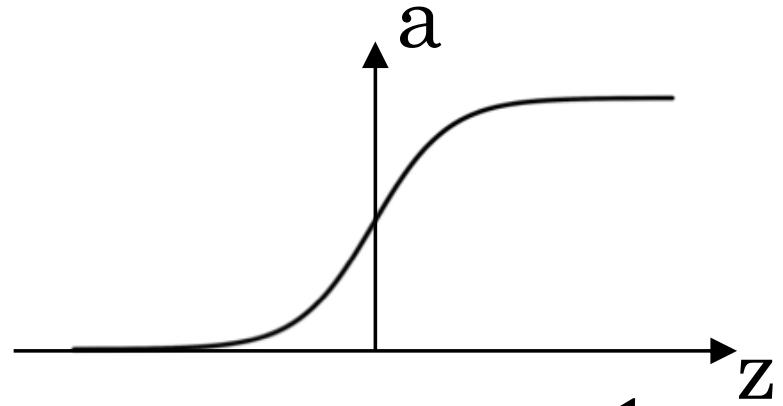
$$\rightarrow a^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

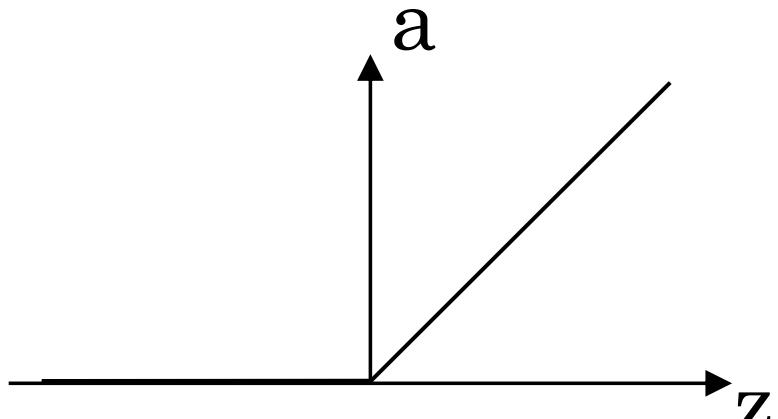
$$\rightarrow a^{[2]} = \sigma(\cancel{z^{[2]}}) \quad \cancel{g^{[2]}(z^{[2]})}$$



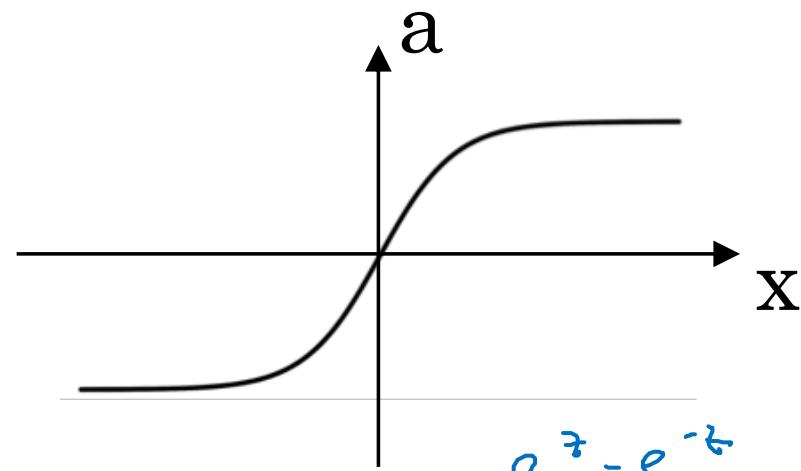
Pros and cons of activation functions



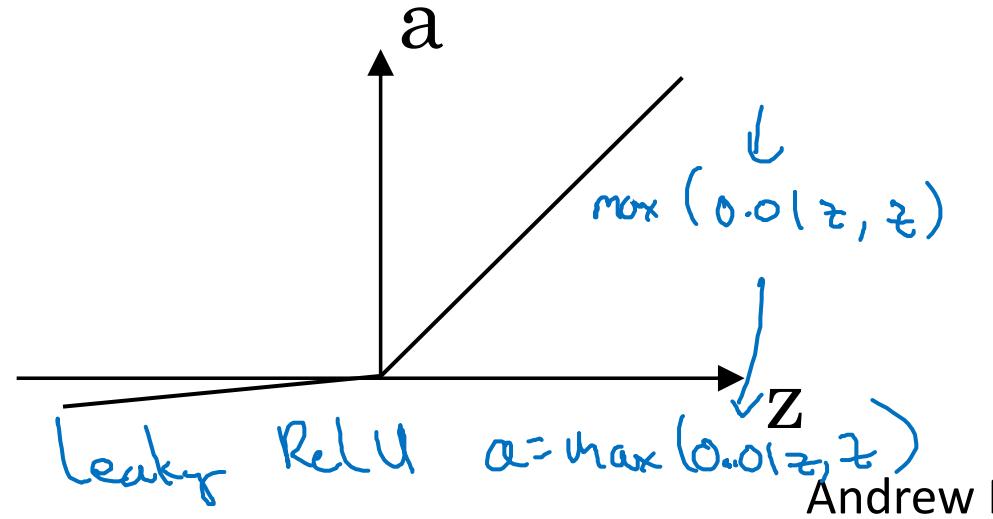
$$\text{sigmoid: } a = \frac{1}{1 + e^{-z}}$$



$$\text{ReLU} \quad a = \max(0, z)$$



$$\tanh: \quad a = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$



$$\text{Leaky ReLU} \quad a = \max(0.01z, z) \quad \text{Andrew Ng}$$

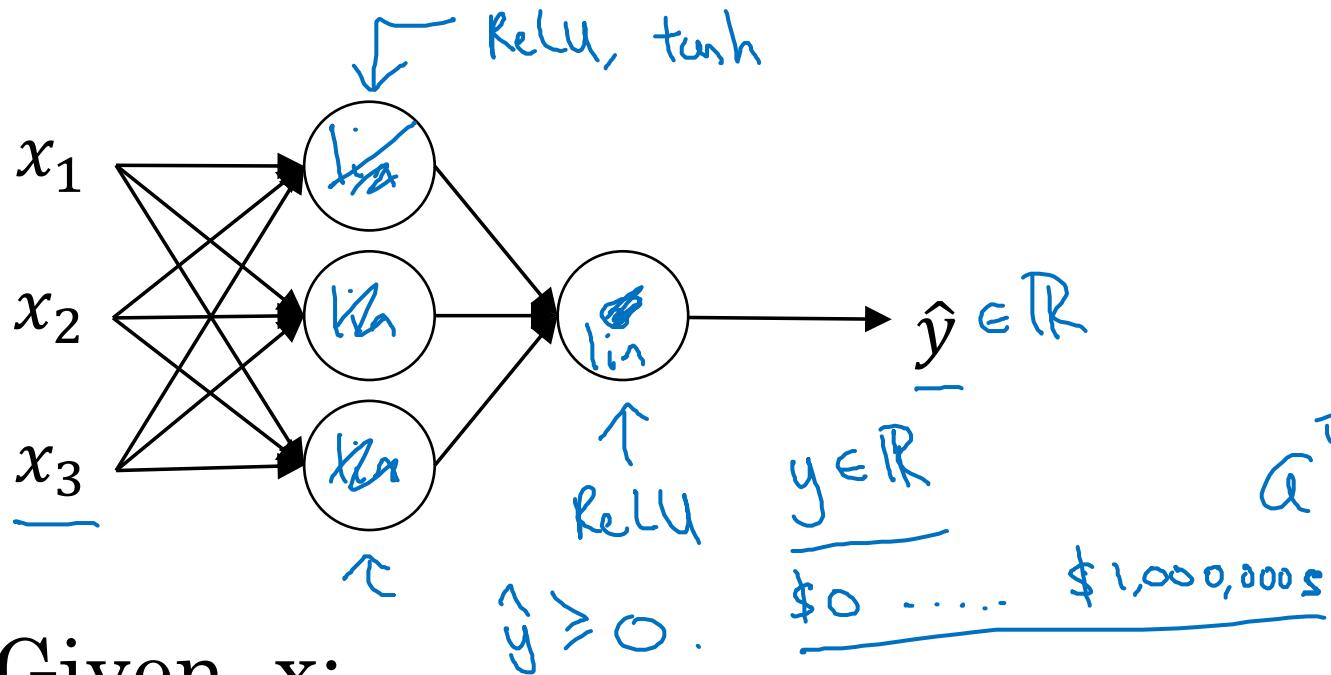


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One hidden layer Neural Network

Why do you
need non-linear
activation functions?

Activation function



$$a^{[1]} = z^{[1]} = \underbrace{W^{[1]}x + b^{[1]}}_{a^{[1]}}$$

$$a^{[2]} = z^{[2]} = \underbrace{W^{[2]}a^{[1]} + b^{[2]}}_{a^{[2]}}$$

$$a^{[2]} = W^{[2]} \left(\underbrace{W^{[1]}x + b^{[1]}}_{a^{[1]}} \right) + b^{[2]}$$

$$= \underbrace{(W^{[2]}W^{[1]})}_{w'} x + \underbrace{(W^{[2]}b^{[1]} + b^{[2]})}_{b'}$$

$$= \underbrace{w'x + b'}_{g(z) = z}$$

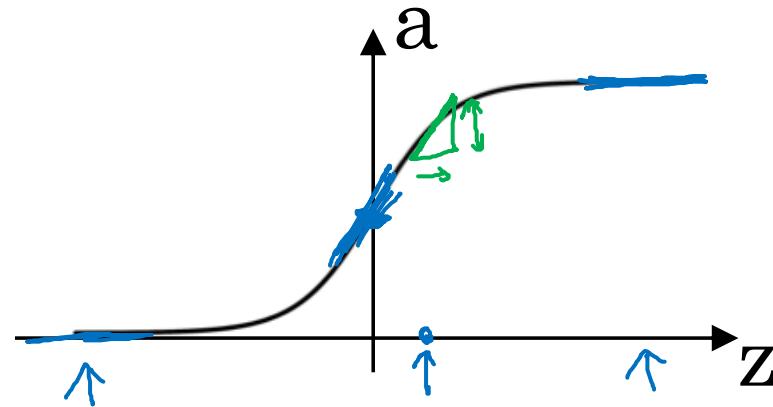


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One hidden layer
Neural Network

Derivatives of
activation functions

Sigmoid activation function



$$g(z) = \frac{1}{1 + e^{-z}}$$

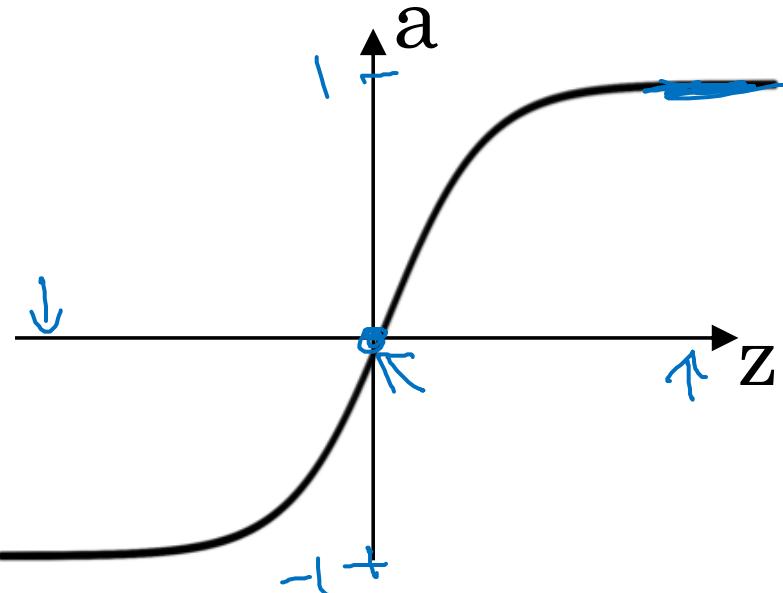
$$a = g(z) = \frac{1}{1 + e^{-z}}$$

$$\begin{aligned}
 g'(z) &= \boxed{\frac{d}{dz} g(z)} \\
 &= \frac{1}{1 + e^{-z}} \left(1 - \frac{1}{1 + e^{-z}} \right) \\
 &= g(z) \left(1 - g(z) \right) \quad \leftarrow \quad \boxed{g'(z) = a(1-a)} \\
 &= \boxed{a(1-a)}
 \end{aligned}$$

$$\begin{aligned}
 z = 10. \quad g(z) &\approx 1 \\
 \frac{d}{dz} g(z) &\approx 1(1-1) \approx 0 \\
 z = -10. \quad g(z) &\approx 0 \\
 \frac{d}{dz} g(z) &\approx 0 \cdot (1-0) \approx 0 \\
 z = 0. \quad g(z) &= \frac{1}{2} \\
 \frac{d}{dz} g(z) &= \frac{1}{2}(1-\frac{1}{2}) = \frac{1}{4}
 \end{aligned}$$

Andrew Ng

Tanh activation function



$$g(z) = \tanh(z)$$

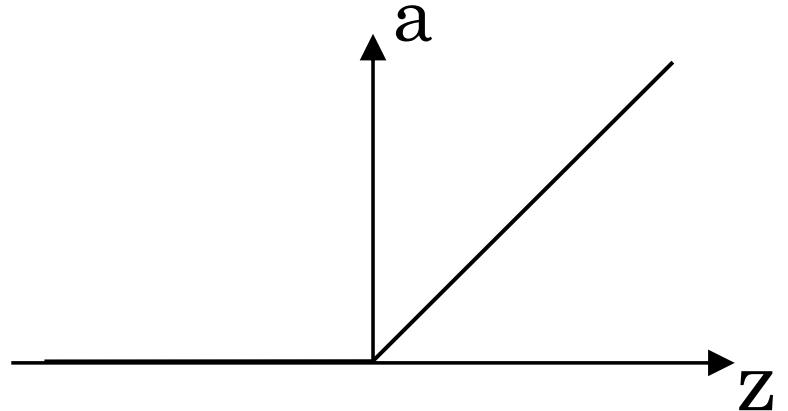
$$= \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$\begin{aligned} g'(z) &= \frac{d}{dz} g(z) = \text{slope of } g(z) \text{ at } z \\ &= \underline{\underline{1 - (\tanh(z))^2}} \leftarrow \end{aligned}$$

$$a = g(z), \quad g'(z) = 1 - a^2$$

$$\left| \begin{array}{ll} z = 10 & \tanh(z) \approx 1 \\ & g'(z) \approx 0 \\ z = -10 & \tanh(z) \approx -1 \\ & g'(z) \approx 0 \\ z = 0 & \tanh(z) = 0 \\ & g'(z) = 1 \end{array} \right.$$

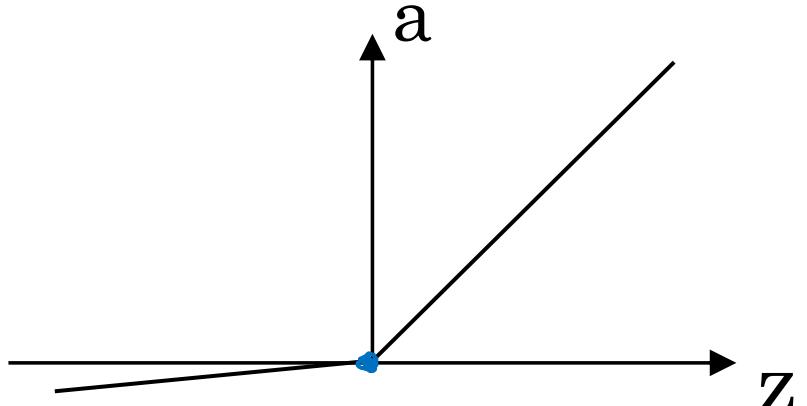
ReLU and Leaky ReLU



ReLU

$$g(z) = \max(0, z)$$

$$\Rightarrow g''(z) = \begin{cases} 0 & \text{if } z < 0 \\ -1 & \text{if } z \geq 0 \\ \text{undefined} & \text{if } z = 0 \end{cases}$$



Leaky ReLU

$$g(z) = \max(0.01z, z)$$

$$g'(z) = \begin{cases} 0.01 & \text{if } z < 0 \\ 1 & \text{if } z \geq 0 \end{cases}$$



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One hidden layer
Neural Network

Gradient descent for
neural networks

Gradient descent for neural networks

Parameters: $(\omega^{[1]}, b^{[1]}, \dots, \omega^{[L]}, b^{[L]})$ $n_x = n^{[0]}, n^{[1]}, \dots, \underline{n^{[L]}} = 1$

Cost function: $J(\underbrace{\omega^{[1]}, b^{[1]}, \dots, \omega^{[L]}, b^{[L]}}, \underbrace{\hat{y}_i}_{\in \mathcal{A}^{[L]}}) = \frac{1}{m} \sum_{i=1}^m l(\hat{y}_i, y_i)$

Gradient Descent:

→ Repeat {

→ Compute predict $(\hat{y}^{(i)}, i=1 \dots m)$

$$\frac{\partial J}{\partial \omega^{[l]}} = \frac{\partial J}{\partial \omega^{[l]}} , \quad \frac{\partial J}{\partial b^{[l]}} = \frac{\partial J}{\partial b^{[l]}} , \dots$$

$$\omega^{[l]} := \omega^{[l]} - \alpha \frac{\partial J}{\partial \omega^{[l]}}$$

$$b^{[l]} := b^{[l]} - \alpha \frac{\partial J}{\partial b^{[l]}}$$

↳

Formulas for computing derivatives

Forward propagation:

$$z^{[1]} = w^{[1]}X + b^{[1]}$$

$$A^{[1]} = g^{[1]}(z^{[1]}) \leftarrow$$

$$z^{[2]} = w^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g^{[2]}(z^{[2]}) = \underline{\underline{\sigma(z^{[2]})}}$$

Back propagation:

$$dz^{[2]} = A^{[2]} - Y \leftarrow$$

$$dW^{[2]} = \frac{1}{m} dz^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} \underline{\text{np.sum}}(dz^{[2]}, \underline{\text{axis=1}}, \underline{\text{keepdims=True}})$$

$$dz^{[1]} = \underbrace{w^{[2]T} dz^{[2]}}_{(n^{[2]}, m)} \times \underbrace{g^{[2]'}(z^{[2]})}_{\text{element-wise product}} \underbrace{(n^{[1]}, m)}$$

$$dW^{[1]} = \frac{1}{m} dz^{[1]} X^T$$

$$\cancel{db^{[1]} = \frac{1}{m} \text{np.sum}(dz^{[1]}, \text{axis=1}, \underline{\text{keepdims=True}})}$$

$$Y = [y^{(1)}, y^{(2)}, \dots, y^{(m)}]$$

$$(n^{[1]}) \leftarrow$$

$$\cancel{(n^{[2]}, 1) \leftarrow}$$



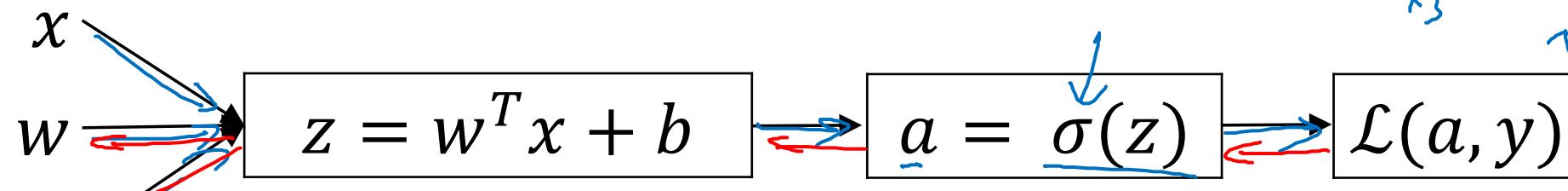
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One hidden layer
Neural Network

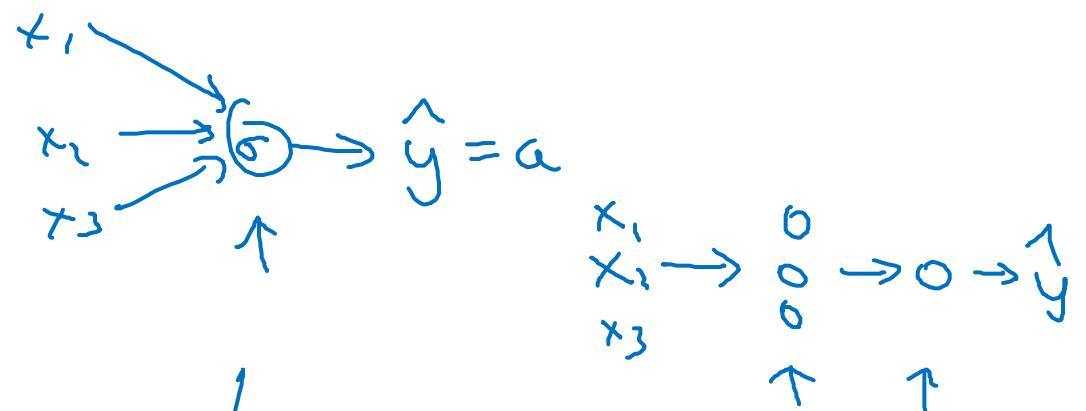
Backpropagation
intuition (Optional)

Computing gradients

Logistic regression



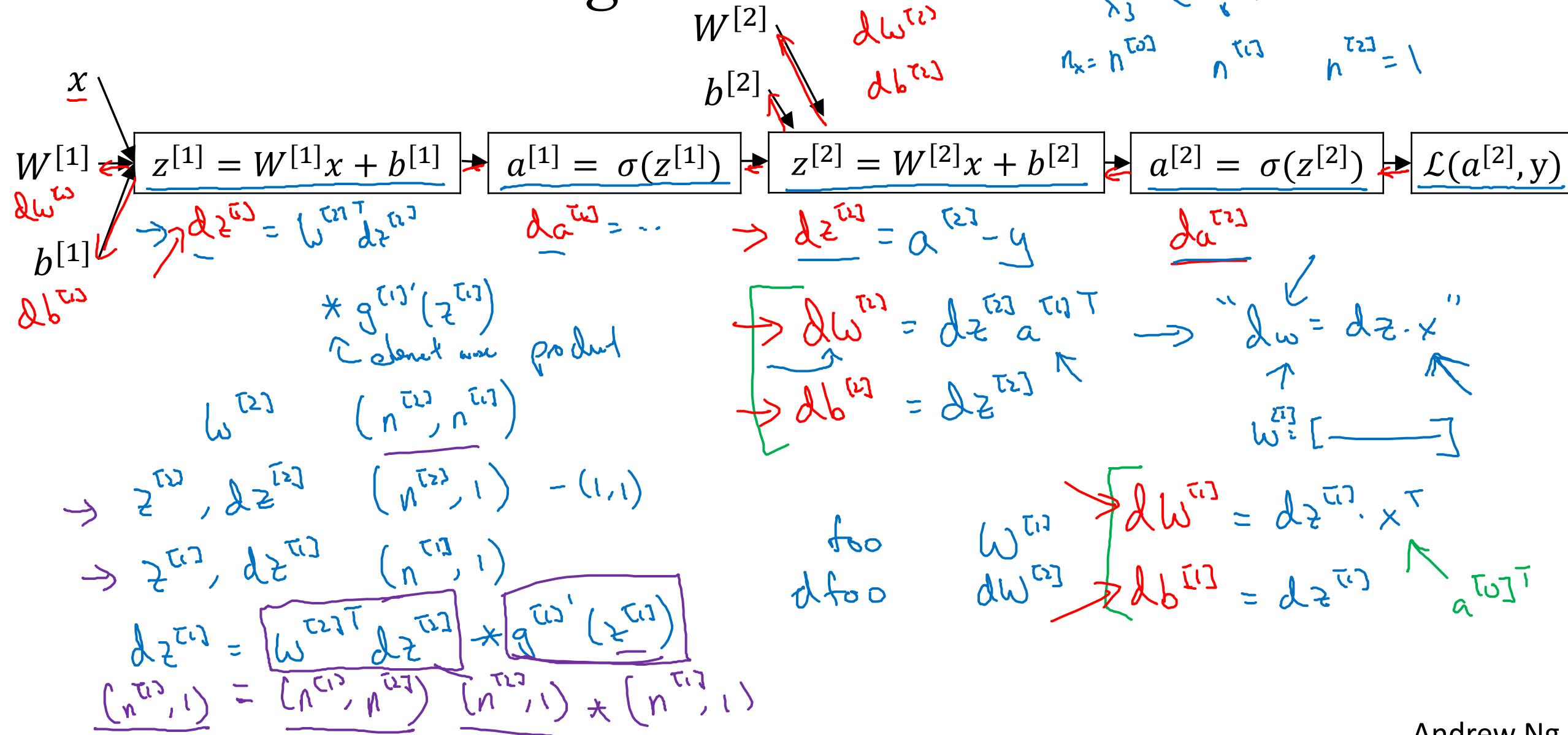
$$\begin{aligned} \frac{\partial z}{\partial w} &= x \\ \frac{\partial z}{\partial b} &= 1 \\ \frac{\partial z}{\partial a} &= g'(z) \\ g(z) &= \sigma(z) \\ \frac{\partial \mathcal{L}}{\partial z} &= \frac{\partial \mathcal{L}}{\partial a} \cdot \frac{\partial a}{\partial z} \\ "dz" &= "da" \end{aligned}$$



$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial a} &= \frac{d}{da} \mathcal{L}(a, y) = -y \log a - (1-y) \log(1-a) \\ &= -\frac{y}{a} + \frac{1-y}{1-a} \end{aligned}$$

$$\frac{d}{dz} g(z) = g'(z)$$

Neural network gradients



Summary of gradient descent

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

Vectorized implementation:

$$\begin{aligned} z^{[1]} &= \underbrace{w^{[1]} x + b^{[1]}}_{\text{Implementation}} \\ a^{[1]} &= g^{[1]}(z^{[1]}) \end{aligned}$$

$$Z^{[1]} = \begin{bmatrix} | & | & | & | \\ z^{1} & z^{[1](2)} & \dots & z^{[1](n)} \\ | & | & | & | \end{bmatrix}$$

$$\begin{aligned} z^{[1]} &= w^{[1]} X + b^{[1]} \\ A^{[1]} &= g^{[1]}(Z^{[1]}) \end{aligned}$$

Summary of gradient descent

$$\underline{dz}^{[2]} = \underline{a}^{[2]} - \underline{y}$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

(n^{T₁}, 1)

$$dW^{[1]} = dz^{[1]} X^T$$

$$db^{[1]} = dz^{[1]}$$

$$\underline{dZ}^{[2]} = \underline{A}^{[2]} - \underline{Y}$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} np.sum(dZ^{[2]}, axis = 1, keepdims = True)$$

$$dZ^{[1]} = \underbrace{W^{[2]T} dZ^{[2]}}_{(n^{T₂}, m)} * \underbrace{g^{[1]'}(Z^{[1]})}_{(n^{T₁}, m)}$$

elementwise product

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} np.sum(dZ^{[1]}, axis = 1, keepdims = True)$$

$$J(\cdot) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}_i, y_i)$$

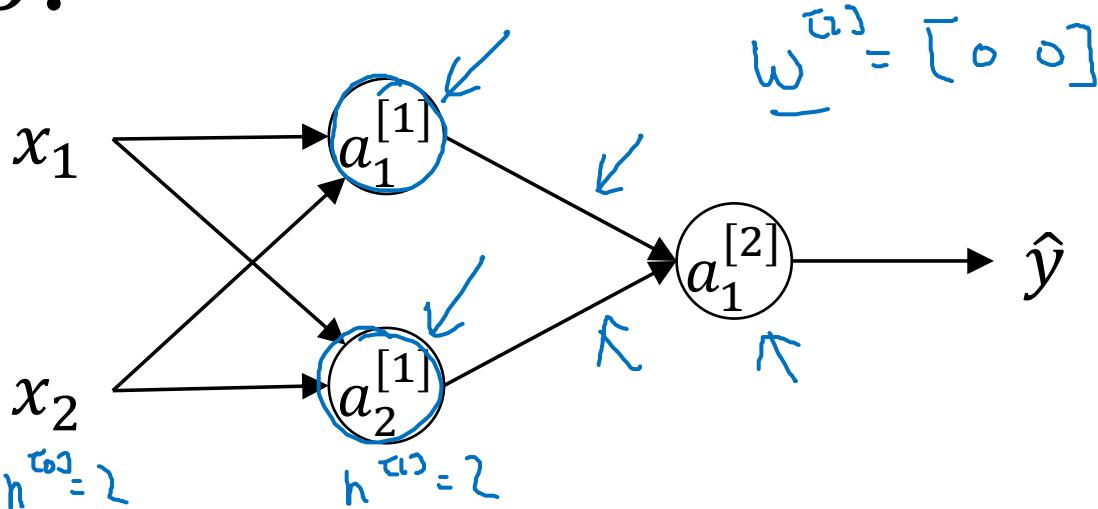


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One hidden layer
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Random Initialization

What happens if you initialize weights to zero?



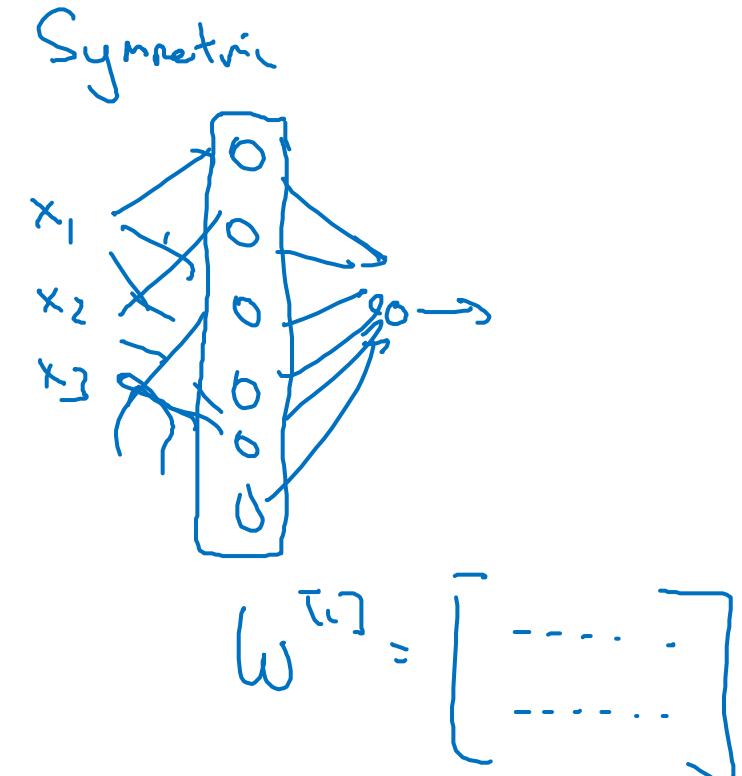
$$W_1^{[1]} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad b_1^{[1]} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$a_1^{[1]} = a_2^{[1]}$$

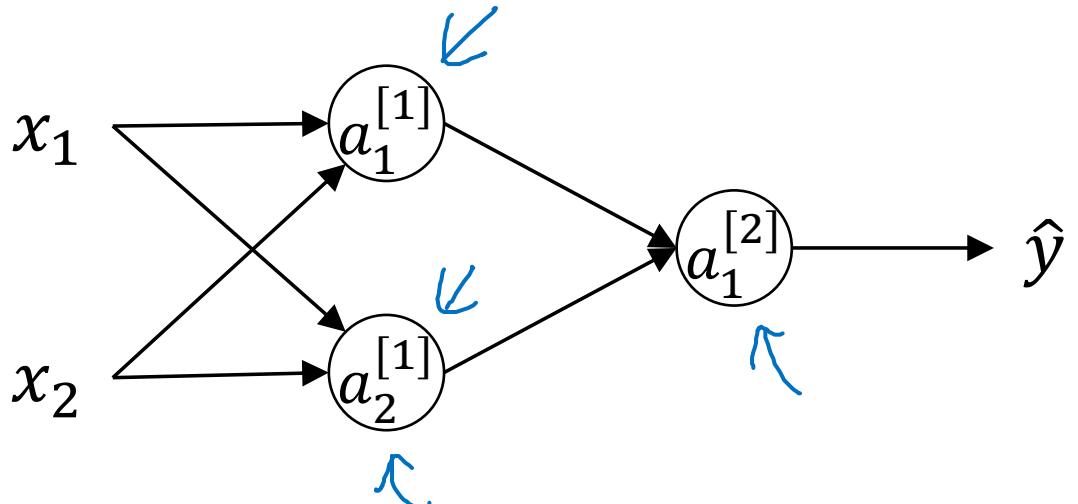
$$\delta z_1^{[1]} = \delta z_2^{[1]}$$

$$\delta w = \begin{bmatrix} u & v \\ u & v \end{bmatrix}$$

$$w^{[1]} = w^{[1]} - \lambda \delta w$$



Random initialization



$$\begin{aligned} \rightarrow w^{[1]} &= \text{np.random.randn}(2, 2) \times \frac{0.01}{100?} \\ b^{[1]} &= \text{np.zeros}(2, 1) \\ w^{[2]} &= \text{np.random.randn}(1, 2) \times 0.01 \\ b^{[2]} &= 0 \end{aligned}$$

$$\begin{aligned} z^{[1]} &= w^{[1]} \times + b^{[1]} \\ a^{[1]} &= g^{[1]}(z^{[1]}) \end{aligned}$$

