

# CS 230: Image Segmentation & Object Detection of Lunar Landscape

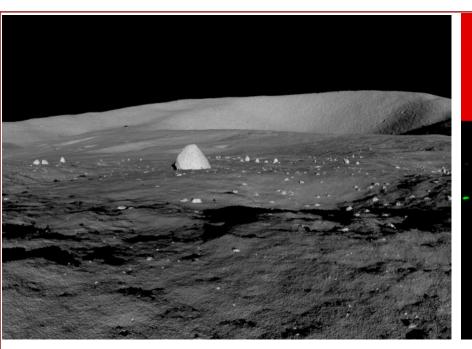
Youtube. Link: https://youtu.be/P1EmjuQdJ2s

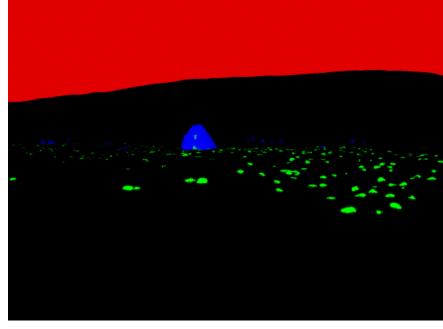
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Stanford **CS** Department

#### Introduction and Motivation

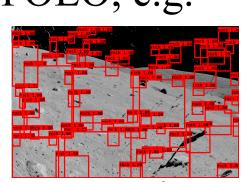


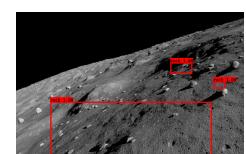


- Use the synthetic image (left) and segmentation (left) to train model
- Segment the synthetic lunar landscape
- Segment the real lunar landscape
- To see the possibility of lunar auto-driving

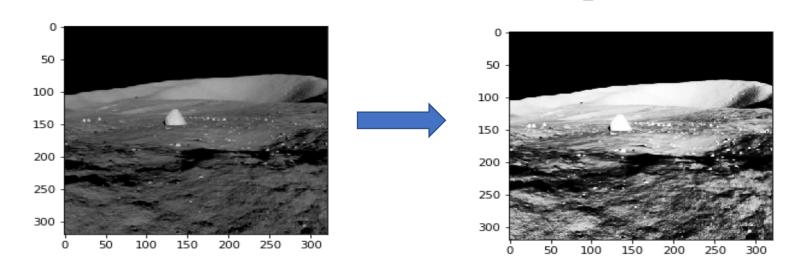
# Dataset and Preprocessing

- Ishigami Laboratory group of Keio University: Artificial Lunar Landscape data set
- 9700 images
- Training Set: 6400
- Validation Set: 2000
- Eye balling defect images and rock labels for YOLO, e.g.





Increase the contrast ratio of inputs:

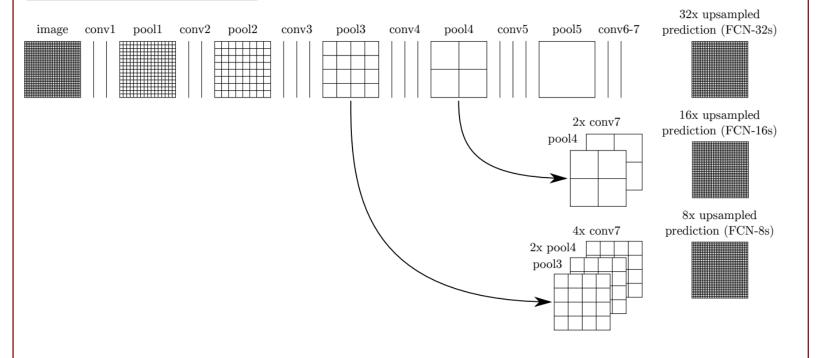


#### Model

### YOLOv2

- Trained with YOLOv2 pretrained weights (full YOLO)
- Learning rate: 0.0001 Optimization: Adam
- Anchors: 5 anchor boxes
- Grids: 13 × 13

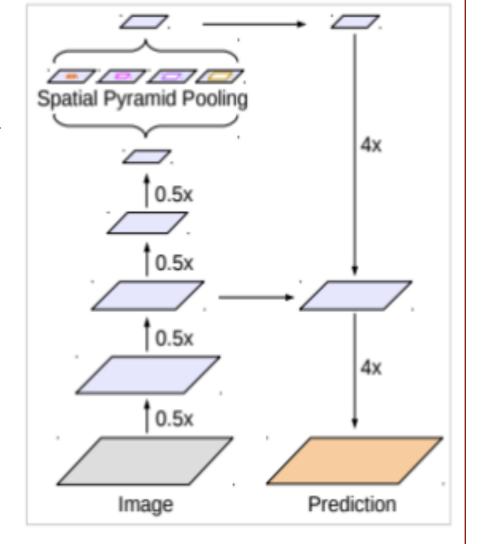
### FCN-8S



- Trained from VGG-16 layer 15
- Learning rate: 0.0005
- Optimization: Adam

# Deeplabv3+

- Learning rate: 0.0005 and then 0.0007 to overcome local minimum
- Optimization: Adam



## Result and Comparison



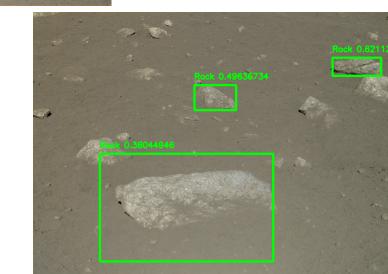
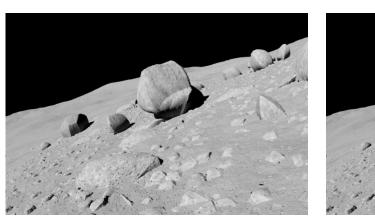


Figure 1: YOLOv2 rock detection on real lunar surface



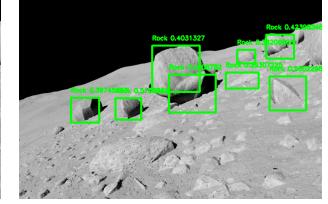
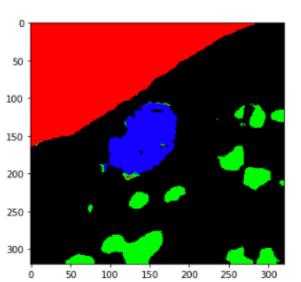


Figure 2: YOLOv2 rock detection on synthetic lunar surface image (mAP: 63.4%)



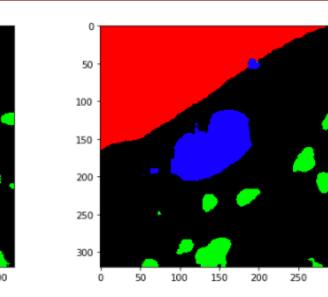
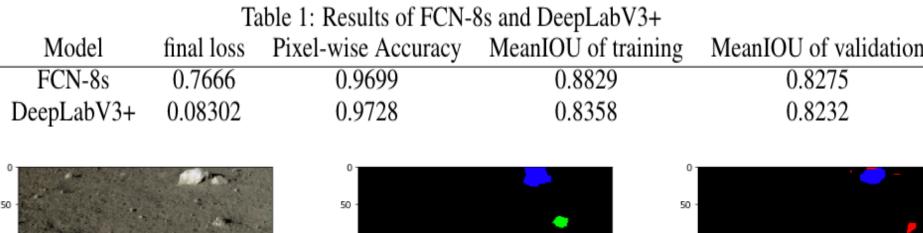


Figure 3: FCN and Deeplab comparison on validation image set of synthetic lanscapes. (a) Cleaned ground truth; (b) FCN-8s prediction; (c) DeeplabV3+ prediction.



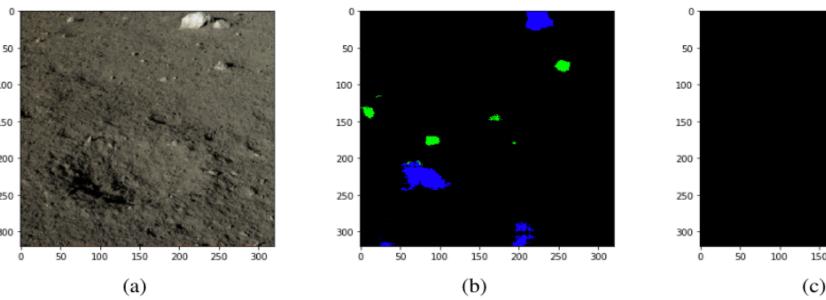


Figure 4: FCN and Deeplab comparison on real moon surface . (a) Cleaned ground truth; (b) FCN-8s prediction; (c) DeeplabV3+ prediction.

## Future Improvement

- More realistic synthetic lunar surface will help a lot.
- Data augment the synthetic image and make it more like the real one.
- Improve data label and use data from different distributions

#### Reference

- S Ghosh, N Das, I Das, and U Maulik. Understanding deep learningtechniques for image segmentation.ACM Computing Surveys (CSUR), 52(4):1–35, 2019.
- J Redmon and A Farhadi. Yolo9000: Better, faster, stronger. arxiv 2016.arXiv preprintarXiv:1612.08242.
- J. Long, E. Shelhamer, and T. Darrell. Fully convolutional networks for semanticsegmentation. InProceedings of the IEEE conference on computer vision and pattern recognition, pages 3431–3440, 2015.
- 4. L. Chen, G. Papandreou, F. Schroff, and H. Adam. Rethinking atrousconvolution for semantic image segmentation.arXiv preprint arXiv:1706.05587, 2017.