

HATRNet: Human Activity/Transition Recognition using Deep Neural Networks

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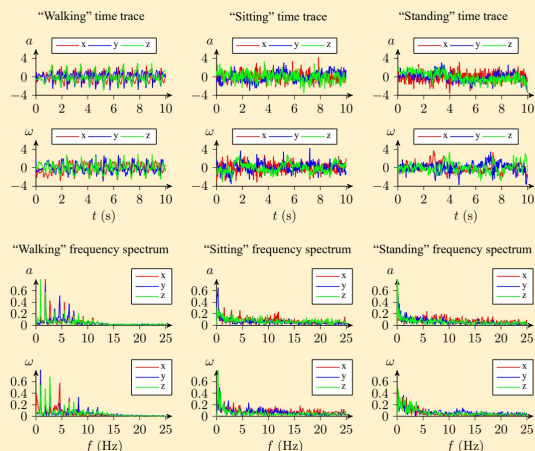


BACKGROUND and MOTIVATION

- Human Activity Recognition has great potential for customized healthcare
- Smartphones incorporate sensors (accelerometer, gyroscope etc.)
- Sensor data can be used to classify human activities and transitions
- Improvements compared to state of the art:
 - Advanced preprocessing including data augmentation
 - End-to-end deep learning solution (no feature extraction)
 - Improved architecture enabling accurate classification of transitions

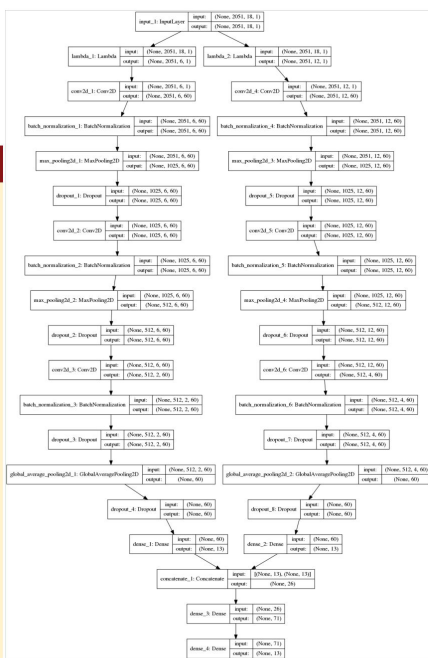
1. DATASET

- SBHAR dataset of 6 activities and 6 postural transitions from the Galaxy SII
- 3-axial linear acceleration and 3-axial angular velocities traces at 50 Hz
- Augmented to 3,640 examples with no feature selection (beyond FFT)



2. NEURAL NETWORK ARCHITECTURE

Siamese (non-weight sharing) CNN



REFERENCES

[1] L. Hwang, D. Chen, A. Sanku, S. Park, and J. Park, "Position-based human activity recognition using smartphone," *Measurement*, vol. 173, pp. 764-765, Jan. 2020.
 [2] J. Wang, J. Wang, and J. Wang, "The application of deep learning neural network for human activity," *2018*.
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 [5] D. P. King, M. H. Hwang, and J. Tang, "Multi-modal deep learning for human activity recognition using smartphone data," *Measurement*, vol. 120, pp. 108-116, 2018.
 [6] S. K. Saha, S. K. Saha, and S. K. Saha, "Human activity recognition using an accelerometer in a mobile device," *International Journal of Computer Science and Information Technology*, vol. 10, pp. 100-104, 2017.
 [7] J. Wang, A. Sanku, S. Park, and J. Park, "Position-based human activity recognition using smartphone," *Measurement*, vol. 173, pp. 764-765, Jan. 2020.
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 [9] L. Hwang, D. Chen, A. Sanku, S. Park, and J. Park, "Position-based human activity recognition using smartphone," *Measurement*, vol. 173, pp. 764-765, Jan. 2020.
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FUTURE WORK

- Model ensembling using data representations from sequence models
- Implement the model on a smartphone for real-time inference
- Incorporate frequency and phase traces into the sequence model

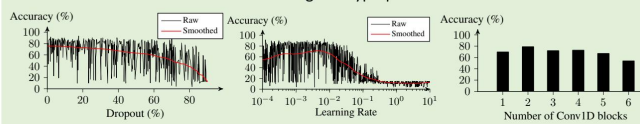
Siamese (non-weight sharing) CNN

- Left subnetwork takes time traces as input (6 zero-padded channels)
- Right subnetwork takes frequency and phase traces as input (12 interpolated channels)
- Late sensor fusion employed for encoded, efficient feature extraction
- Conv2D filter size: 1x14 Conv2D filter size: 3x42 Filter #: 60 learning rate: 0.0026

Sequence (LSTM) Model

- Takes time traces as input (6 channels of variable length)
- Two LSTM layers (128 to 32 output channels)

Random Coarse- to Fine-grain Hyperparameter Search



3. RESULTS and DISCUSSION

Literature comparison (grouped postural transitions):

	SVM, 561 features extracted [1]						CNN (2.5 second traces) [2]						
	WA	WU	WD	SI	ST	LD	PT	WA	WU	WD	SI	ST	LD
WA	1834	64	5	3	2	0	1	487	0	9	0	0	0
WU	10	1743	51	5	5	0	16	2	468	0	0	0	1
WD	0	2	1671	1	7	0	1	0	0	420	0	0	0
SI	0	0	0	1875	94	6	3	0	2	0	443	46	0
ST	0	2	0	109	2049	0	11	0	0	0	16	516	0
LD	0	0	0	1	0	2148	2	0	0	0	0	0	537
PT	0	1	2	0	0	0	1036						

HATRNet Results (ungrouped postural transitions):

Siamese (non-weight sharing) CNN												
	WA	WU	WD	SI	ST	LD	STSI	STSL	LSI	STL	LST	
WA	21	0	1	0	0	0	0	0	0	0	0	0
WU	0	36	0	0	0	1	0	0	0	0	0	0
WD	0	0	35	0	0	0	0	0	0	0	0	0
SI	0	0	0	29	4	0	0	0	0	0	0	0
ST	0	0	0	2	27	0	0	0	0	0	0	0
LD	0	0	0	0	0	26	0	0	0	0	0	0
STSI	0	0	0	0	0	0	19	0	0	0	0	0
STSL	0	0	0	0	0	0	0	11	0	0	0	0
LSI	0	0	0	0	0	0	0	0	15	0	0	0
STL	0	0	0	0	0	1	0	1	0	10	0	0
LST	0	0	0	0	0	0	0	0	0	0	7	0

Architecture Comparison:

	CNN1	CNN2	LSTM	SVM [1]	Perceptionnet (CNN) [2]
Number of categories	12	7	12	7	6
Error Rate	3.29 %	0.82 %	18.11 %	3.22 %	2.75 %