



# Content Recognition in Surgical Videos



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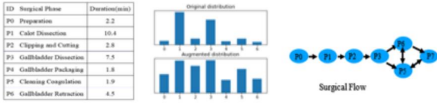
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## Overview

- Advances in Computer Vision promise great improvements in surgical work-flow detection.
- We built a CNN + LSTM model to detect work flow from surgical videos.
- Prior knowledge of surgical flow applied to achieve accuracy of 88%.
- We built tool detection model to evaluate tool importance in phase detection

## Data

- 80 videos of cholecystectomy are split into 50/25/25 train/dev/test ratio
- Video converted to 224 x 224 RGB images at 5 FPS
- The labeled data was unbalanced, and data augmentation was used
- Surgical flow shows Markov chain as below and used for optimization



- Time step of 25 used for LSTM processing.
- The images showed tool rotations for the same activity (below) and random horizontal flips added to augment the data
- Tool detection used 1250 images with bounding boxes for train set. The train/dev/test ratio of 70/15/15 is used.

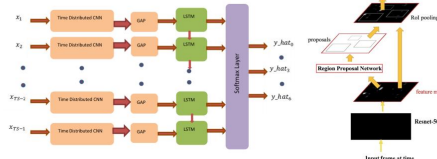


## CNN+LSTM Training

Training Method	Advantages	Disadvantages
<b>Train CNN and LSTM Separately</b>	<ul style="list-style-type: none"> <li>Hyper-parameters can be chosen independently as separate loss functions are used</li> <li>Computationally less expensive</li> </ul>	<ul style="list-style-type: none"> <li>Sub-optimal due to significant intra-class variance and limited interclass variance of visual features</li> </ul>
<b>End to End CNN + LSTM training</b>	<ul style="list-style-type: none"> <li>The LSTM error is backpropagated to CNN and CNN training is helped by sequence discrimination of LSTM</li> </ul>	<ul style="list-style-type: none"> <li>Restriction on hyper parameter selection as both the models share same optimizer/loss function in Keras</li> </ul>
<b>Stateful LSTM</b>	<ul style="list-style-type: none"> <li>Captures correlations across time steps</li> <li>Useful for small batches as Keras resets the LSTM internal states every batch size</li> </ul>	<ul style="list-style-type: none"> <li>Care must be taken to maintain temporal information in the input data (no shuffling). Otherwise will degrade the performance</li> </ul>

## Model

- Time Distributed CNN with Global Average Pool Layer (GAP) feeds LSTM
- LSTM layer of size 2048 with a Dense layer followed by Softmax
- Nadam optimizer with learning rate of 0.00001 and rate decay of 0.004
- Batchsize = 8, Dropouts (0.5) and L2 regularization (0.01) used for LSTM



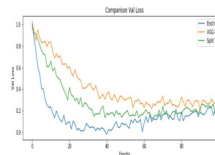
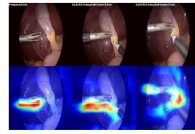
### Phase detection

- Model takes frames with bounding boxes as input. Outputs tool label, confidence and localization information.
- Faster R-CNN has 2 networks, region proposal network(RPN) for generating proposals and detector. We use Resnet50 as our CNN.
- We tuned learning rate, bbox threshold, type of CNN's to get to 80% accuracy.

### Tool detection

## Error Analysis

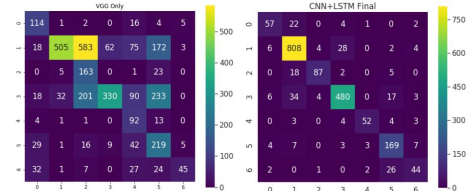
- Activation map used to understand mis-detections of CNN output
- Loss function used to analyze overall convergence and performance
- Early stopping is used to prevent overfitting



- Tool detection model got accuracy of 80%, on-par with state-of-the-art model. Hand tuned weights and tool predictions are combined with phase detector model.
- This approach showed improvement in F1 scores.
- Frames with gas were mis-classified as bag in many examples

## Results

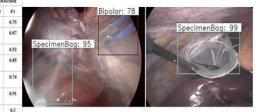
CNN+LSTM Final	Precision	recall	f1-score	support
(0) Preparation	0.76	0.66	0.71	86
(1) CalotTriangleDissection	0.91	0.95	0.93	852
(2) ClippingCutting	0.91	0.78	0.84	112
(3) GallbladderDissection	0.92	0.88	0.9	544
(4) GallbladderPackaging	0.9	0.79	0.84	66
(5) CleaningCoagulation	0.76	0.88	0.81	193
(6) GallbladderRetraction	0.7	0.59	0.64	75
<b>Overall</b>	<b>0.88</b>	<b>0.88</b>	<b>0.88</b>	<b>1,928</b>



Confusion matrix for model predictions.

## Tool Detection Results

	Resnet50-CNN+LSTM				Resnet50-ToolDetection			
Case	Precision	Recall	F1	Tool	Precision	Recall	F1	Tool
Preparation	0.9	0.96	0.93	0.75	0.86	0.86	0.79	0.79
Clipping Cutting	0.98	0.92	0.95	0.87	0.86	0.85	0.87	0.87
Calot Triangle Dissection	0.9	0.92	0.91	0.88	0.92	0.92	0.92	0.92
Gallbladder Dissection	0.97	0.97	0.97	0.98	0.97	0.97	0.97	0.97
Gallbladder Packaging	0.8	0.82	0.81	0.75	0.83	0.83	0.78	0.78
Cleaning Coagulation	0.8	0.87	0.83	0.81	0.83	0.83	0.81	0.81
Gallbladder Retraction	0.7	0.68	0.69	0.68	0.63	0.63	0.63	0.63
Average	0.88	0.88	0.88	0.83	0.88	0.88	0.88	0.88



## Conclusion/Future Work

- End to end training of CNN+LSTM provides best results of 88% accuracy
- Prediction accuracy can be improved with prior knowledge of surgical flow
- We achieved 80% accuracy in tool detection and this information can help surgical phase detection.
- We plan to explore stacked LSTM and stateless LSTM to improve the accuracy
- Use tool detection to improve the confidence of surgical phase detection

## Reference

[1] Y. Jin et al. "SV-RCNet: Workflow Recognition from Surgical Videos Using Recurrent Convolutional Network," in IEEE Transactions on Medical Imaging, vol. 37, no. 5, pp. 1114-1126, May 2018.  
 [2] O. Dergachyova, D. Bouget, A. Hualimé, X. Morandi, and P. Jannin, "Automatic data-driven real-time segmentation and recognition of surgical workflow," Int. J. Comput. Assist. Radiol. Surgery, vol. 11, no. 6, pp. 1-11, 2017.  
 [3] Amy Jin, Serena Yeung, Jeffrey Jopling, Jonathan Krause, Dan Azagury, Arnold Milstein, and Li Fei-Fei (2017). Tool Detection and Operative Skill Assessment in Surgical Videos Using Region-Based Convolutional Neural Networks Stanford University.