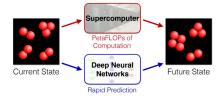
# Stanford Future Prediction in Brownian Dynamics Simulations Using Deep Neural Networks Brian K. Ryu (bryu@stanford.edu)

### Motivation

- · Scientists utilize molecular dynamics (MD) and Brownian dynamics (BD) to study dynamic or non-equilibrium properties of materials.1
- The principle challenge of MD/BD simulations is the prohibitive computational cost to simulate phenomena that occur at long time scales.
- The goal is to predict the future states of simulations using deep neural networks and bypass explicit computation of every time step:



# **Data & Features**

- 14,400 simulation trajectories list of particle positions (x,v,z) at a given time step - generated using the LAMMPS Molecular Dynamics Simulator.<sup>2</sup>
- Simulation undergoes slow arrested phase separation with different system parameters (volume fraction and interparticle attraction strength).3



Images rendered from simulation snapshots undergoing slow phase separation, separated by  $10^5$  time steps. Particle colors indicate number of contacts

- Each input and output snapshot contains (x, y, z) positions of 8,788 particles: i.e. 26,364 floating point numbers.
- Particle motion is mildly stochastic and largely deterministic; particles with few contacts are free to diffuse while particles with many contacts move less.

### Model

**Model Architecture** 

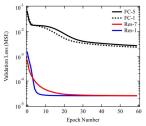
#### Input Trajectory Flatten and Compute Output Layer Displacement $(8788 \times 3)$ Normalize $(8788 \times 3)$ Residual **Preprocess Blocks**

- · Mean-squared error (MSE) for loss function.
- Use Adam optimizer with L2 regularization.
- · Scan over architectures and hyperparameters.

#### Residual Block<sup>4</sup> Transfer input positions via residual connection 0 0 Ю Input positions Neural network Displacements Output positions (26364)(26364) predicts displacement

#### Results

- Our model accurately predicts particle positions with small MSE.
- · Residual networks result in significantly smaller loss compared to simple plain networks with only fully connected layers.



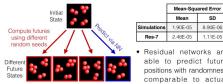
	Mean-Squared Error		
	Training	Validation	Test
FC-1	2.41E-03	2.35E-03	2.34E-03
FC-5	2.81E-03	2.71E-03	2.74E-03
Res-1	2.61E-05	2.55E-05	2.48E-05
Res-3	2.60E-05	2.55E-05	2.48E-05
Res-5	2.60E-05	2.56E-05	2.49E-05
Res-7	2.60E-05	2.55E-05	2.48E-05

Plain (fully connected) Nets: FC-(# of Layers) Residual Nets: Res-(# of Residual Blocks)

### **Discussion and Conclusions**

#### **Bayes Error Quantification**

- · Different random seeds in simulations result in different realizations of future states.
- · Mean-squared difference of particle positions are compared across simulated and predicted outcomes.



Residual networks are able to predict future positions with randomness comparable to actual

Res-7 2.48E-05 1.11E-05

Mean SD

- Compare positions to quantify degree of randomness (signal-to-noise ratio)
- Learning rate  $\alpha = 0.00005$ , achieves slow training but small loss.

L2 regularization (λ = 0.0001) suppresses overfitting.

- . Batch size 512 achieves a balance of speed and performance.
- Residual block size with 3 fully-connected hidden layers each with O(1000) neurons provide accurate displacement predictions

### Conclusions and Future Work

- · Successfully developed a deep neural network for predicting future states in Brownian Dynamics simulations.
- Utilizing a residual network structure to focus on displacement significantly improves performance.
- Future work should visualize and interpret what and how each residual block is computing displacements.
- Future work should extend current architecture for variable number of particles.

## **Acknowledgements and References**

- The author would like to thank Ahmad Momeni and the CS 230 teaching
- staff for helpful discussion and guidance.

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