

A Deep Learning Approach for Human Activity Recognition

Project Category: Other (Time-Series Classification)

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Abstract

The hardware and sensors in smartphones and wearable devices are becoming more powerful and precise every year; the valuable data these sensors collect can be used for more precise Human Activity Recognition. In this paper, we explore implementing both Convolutional Neural Networks and LSTMs to classify 18 unique activities ranging from eating chips to dribbling a ball from labelled, time-series gyroscope and accelerometer data collected from a smartwatch and smartphone. All of our work is located in our public repo [here](#), and the processed data can be accessed [here](#).

1 Introduction

Wearable devices and smartphones are ubiquitous, and a majority of these devices contain many sensors, including Inertial Measurement Units (**IMUs**) such as gyroscopes and accelerometers. As these sensors have become cheaper and more available, an increasing number of people have 'always-on' accelerometers and IMU sensors active. There are an increasing number of machine learning applications for using this data, given how much information can be inferred from them. For example, IMU data can be used for ML-based gesture recognition, like with the Raise to Speak feature on the Apple Watch.

This data could also be used to perform human activity recognition (**HAR**), to recognize the motion characteristics of the user. This has several applications, for example, in healthcare, to measure the activity and fitness characteristics of the user. Some devices do this for fitness tracking, but the potential for activity recognition extends beyond just exercise; the utility of HAR becomes more apparent when it can be used to classify many more everyday activities, such as logging when you brush your teeth, or automatically estimating your food intake based on estimation of when you are eating and drinking.

Using IMU data for this purpose is also often preferable to other modalities; it is privacy-preserving since there is less user-identifiable data compared to audio or camera data, and IMUs tend to be less computationally and power-intensive than other sensors such as cameras and microphones.

2 Related work

Another common method that is proposed to extract frequency-domain features using MFCCs or Spectrograms on the accelerometer data. However, these feature-based approaches require an intricate and extensive knowledge of the domain, and often are time-consuming to both identify and

compute.(1) They are also brittle, and it is difficult to optimize the features end-to-end, since they are the first input to the model (4). As the number of motion activities scale, so does the effort in identifying relevant features. Some previous work (2) has investigated using deep learning for HAR, typically with one-dimensional convolutional neural networks (CNNs) (7).

The experiments by Bevilacqua (3) identify a deep learning approach based on CNNs, but are based on exercises rather than common activities. Their dataset was derived from specially placed sensors on the lower half of the body, which makes it less applicable to a large user base, as most people just have smartphones or smart watches.

Weiss (5) opted to use five distinct algorithms: Random Forests, J48 decision trees, B3 instance-based learning, Naive Bayes, and multi-layer perceptron. Using these algorithms, Weiss was able to obtain an overall accuracy rate of 25.3% with the phone accelerometer data, and 64% accuracy with the watch accelerometer data.

3 Dataset and Features

We are using a brand new **WISDM** dataset (5), released this year by Fordham University which can be downloaded online here. The dataset was created from 15 different participants, each of whom wore a smartwatch on their left wrist, and either a Google Nexus or Samsung Galaxy S5 in their pocket. The phone was placed in their right pocket upright, with the screen of the phone facing away from the body. Each participant performed 18 different activities with each device separately for 4 consecutive minutes each. The full list of activities were: walking, jogging, climbing stairs, sitting, standing, typing, brushing teeth, eating soup, eating chips, eating pasta, drinking from a cup, eating a sandwich, kicking a soccer ball, playing catch with a tennis ball, dribbling a basketball, writing, clapping, and folding clothes.

What makes this dataset fairly unique is that the activities go beyond just motion activities; for example, the dataset contains categories like "brushing teeth" and "eating chips". This gives it applications beyond most other datasets which focus on exercise or motion only.

The gyroscope and accelerometer tri-axial data was sampled at a rate of 20Hz, where each sample contains scalar data about the devices current position in space. Each sample is of the form:

[Participant ID (beginning at 1600)], [timestamp (unix-based)], [x value], [y value], [z value] as shown below in Figure 2.

```
1600,A,252207666810782,-0.36476135,8.793503,1.0550842;
```

Figure 1: Example of accelerometer/gyroscope data



Figure 2: Phone Accel/Gyro Data when Jogging

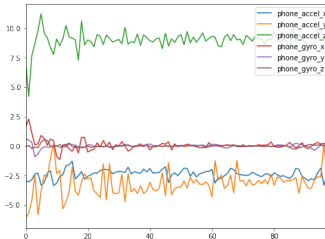


Figure 3: Phone Accel/Gyro Data when eating sandwich

Since the dataset has a hierarchical file structure, (each participant has 18 folders for each activity) we first aggregated the data for each participant together into 15 different data-frames. Next, we merged all phone and watch data from each participant together. We then created sliding windows of approximately 2 seconds with an equivalent stride to slice the sensor data into different parts. Finally, we combined the separated windows for both the phone and watch data.

4 Methodology

More traditional algorithms have been applied to activity recognition, however as previously mentioned this requires an extensive amount of modelling and creating higher level features to represent the problem, and oftentimes this may not be an accurate representation of the problem leading to inaccuracies at prediction time. CNN/LSTM have the capacity to learn temporal dependencies between outputs from the phone/watch sensors, therefore we have opted to implement both an LSTM and CNN architecture for our task. We are using Weiss' (5) best performing algorithm as our baseline since he also trained his models on the WISDM dataset.

5 Model Architecture

Our Convolutional Neural Network consists of 4 Conv1D layers, accompanied with Batch Normalization and Max Pooling layers and lastly a flatten and two dense layers as shown below:

Model: "sequential_12"

Layer (type)	Output Shape	Param #
conv1d_45 (Conv1D)	(None, 98, 2)	38
batch_normalization_45 (Batch Normalization)	(None, 98, 2)	8
max_pooling1d_45 (MaxPooling1D)	(None, 49, 2)	0
conv1d_46 (Conv1D)	(None, 47, 4)	28
batch_normalization_46 (Batch Normalization)	(None, 47, 4)	16
max_pooling1d_46 (MaxPooling1D)	(None, 23, 4)	0
conv1d_47 (Conv1D)	(None, 21, 8)	104
batch_normalization_47 (Batch Normalization)	(None, 21, 8)	32
max_pooling1d_47 (MaxPooling1D)	(None, 10, 8)	0
conv1d_48 (Conv1D)	(None, 8, 16)	400
batch_normalization_48 (Batch Normalization)	(None, 8, 16)	64
max_pooling1d_48 (MaxPooling1D)	(None, 4, 16)	0
flatten_12 (Flatten)	(None, 64)	0
dense_23 (Dense)	(None, 32)	2080
dense_24 (Dense)	(None, 18)	594

Total params: 3,364
Trainable params: 3,304
Non-trainable params: 60

Figure 4: 4ConvLayer Neural Network Architecture

Layer (type)	Output Shape	Param #
lstm_5 (LSTM)	(None, 50, 64)	18176
lstm_6 (LSTM)	(None, 64)	33024
dense_3 (Dense)	(None, 18)	1170

Figure 5: Stacked-LSTM Model Structure

For the LSTM structure, we decided to use a stacked-LSTM structure. We chose to stack multiple recurrent states with multiple memory cells because it allows the model to determine more complex abstractions from the input data. Specifically, we have two LSTM layers, followed by a Dense Layer.

Since we are performing classification on our data, the **Cross Entropy Loss** is a natural loss function to use. For classification problems it is equivalent to the Maximum Likelihood Estimation (MLE). The multi-class Cross Entropy Loss is defined as follows:

$$J = \frac{1}{N} \left(\sum_{i=1}^N y_i - \log(\hat{y}_i) \right)$$

where \hat{y}_i is the predicted label for the i th training example, y_i is the true desired label, and N is the number of training examples.

6 Experiments/Results/Discussion

Comparing LSTM and CNN on both watch and phone data sets, we see that the LSTM performs better than the CNN with 79% vs. 72% accuracy and 74% vs. 50% for each respective dataset. The resulting confusion matrices show that the models on the phone dataset struggle to differentiate between activities that require similar hand movements such as eating chips versus eating soup. Similarly, the models had a difficult time distinguishing between catching, kicking, and dribbling on the watch dataset likely because the hand movements aren't what most distinguishes these activities.

It's worth noting that despite these difficulties, the model still manages to greatly improve upon our baseline from Weiss. Additionally, if we were to group all eating activities together, the accuracy of both models would be much higher.

Phone Results with LSTM for Test Set				
	precision	recall	f1-score	support
catch	0.66	0.68	0.67	534
chips	0.61	0.74	0.67	427
clapping	0.66	0.71	0.69	501
dribbling	0.77	0.68	0.72	610
drinking	0.68	0.58	0.62	628
folding	0.64	0.69	0.67	493
jogging	0.98	0.97	0.97	529
kicking	0.72	0.72	0.72	557
pasta	0.60	0.72	0.65	386
sandwich	0.68	0.62	0.65	552
sitting	0.76	0.77	0.77	503
soup	0.66	0.65	0.66	532
stairs	0.86	0.92	0.89	501
standing	0.81	0.73	0.77	566
teeth	0.71	0.70	0.71	503
typing	0.81	0.75	0.78	531
walking	0.95	0.94	0.95	575
writing	0.76	0.81	0.78	454
accuracy			0.74	9382
macro avg	0.74	0.74	0.74	9382
weighted avg	0.74	0.74	0.74	9382

Figure 6: LSTM results for Phone

Phone Results with CNN for Test Set				
	precision	recall	f1-score	support
catch	0.57	0.48	0.52	644
chips	0.26	0.37	0.31	372
clapping	0.47	0.47	0.47	545
dribbling	0.54	0.62	0.58	462
drinking	0.16	0.42	0.23	208
folding	0.43	0.53	0.47	427
jogging	0.92	0.95	0.93	509
kicking	0.50	0.53	0.52	532
pasta	0.32	0.37	0.34	392
sandwich	0.30	0.32	0.31	473
sitting	0.47	0.40	0.43	606
soup	0.44	0.28	0.34	829
stairs	0.73	0.64	0.68	611
standing	0.70	0.54	0.61	674
teeth	0.47	0.46	0.47	511
typing	0.41	0.46	0.43	438
walking	0.84	0.80	0.82	594
writing	0.48	0.42	0.45	555
accuracy			0.50	9382
macro avg	0.50	0.50	0.50	9382
weighted avg	0.53	0.50	0.51	9382

Figure 7: CNN results for Phone

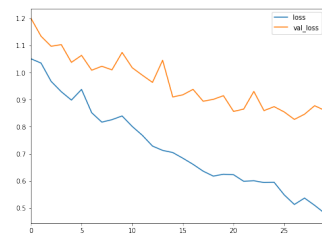


Figure 8: LSTM loss for Phone

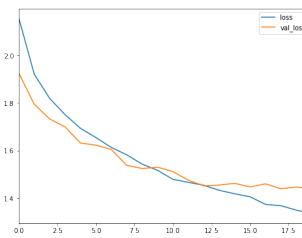


Figure 9: CNN loss for Phone

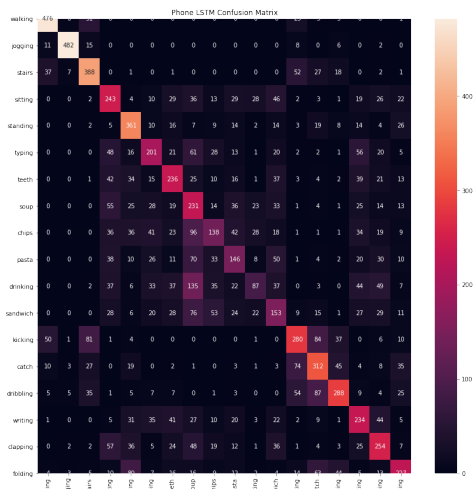


Figure 10: LSTM Confusion Matrix for Phone

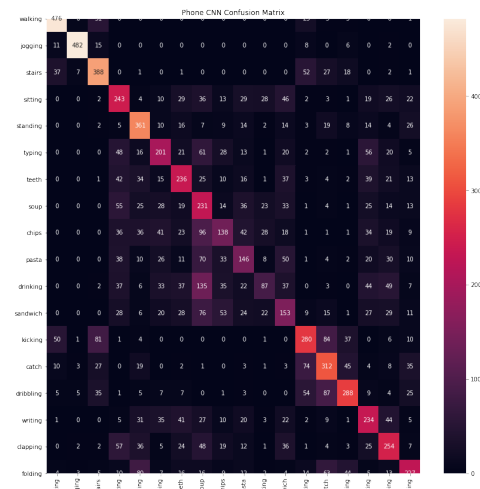


Figure 11: CNN Confusion Matrix for Phone

Watch Results with LSTM for Test Set				
	precision	recall	f1-score	support
catch	0.88	0.85	0.87	820
chips	0.57	0.56	0.56	841
clapping	0.93	0.95	0.94	767
dribbling	0.91	0.89	0.90	835
drinking	0.70	0.69	0.69	871
folding	0.80	0.76	0.78	903
jogging	0.96	0.98	0.97	786
kicking	0.83	0.79	0.81	874
pasta	0.66	0.65	0.66	830
sandwich	0.47	0.53	0.50	743
sitting	0.76	0.74	0.75	831
soup	0.71	0.68	0.69	835
stairs	0.78	0.83	0.80	703
standing	0.79	0.81	0.80	829
teeth	0.89	0.90	0.89	874
typing	0.79	0.85	0.82	740
walking	0.89	0.90	0.89	760
writing	0.86	0.82	0.84	897
accuracy			0.79	14739
macro avg	0.79	0.79	0.79	14739
weighted avg	0.79	0.79	0.79	14739

Figure 12: LSTM results for Watch

Watch Results with CNN for Test Set				
	precision	recall	f1-score	support
catch	0.80	0.88	0.84	319
chips	0.41	0.55	0.47	310
clapping	0.90	0.88	0.89	429
dribbling	0.85	0.88	0.87	393
drinking	0.50	0.63	0.56	363
folding	0.84	0.69	0.76	485
jogging	0.97	0.98	0.97	416
kicking	0.76	0.73	0.75	429
pasta	0.63	0.56	0.59	434
sandwich	0.36	0.36	0.36	400
sitting	0.65	0.57	0.61	495
soup	0.60	0.70	0.65	361
stairs	0.82	0.74	0.78	375
standing	0.73	0.77	0.75	361
teeth	0.82	0.88	0.85	369
typing	0.82	0.67	0.74	520
walking	0.84	0.92	0.88	371
writing	0.75	0.69	0.71	449
accuracy			0.72	7279
macro avg	0.73	0.73	0.72	7279
weighted avg	0.73	0.72	0.72	7279

Figure 13: CNN results for Watch

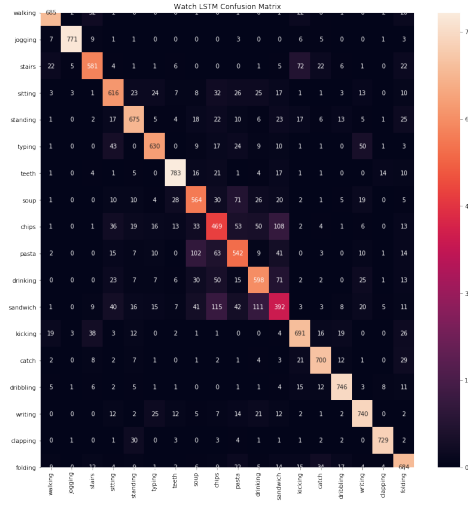


Figure 14: LSTM Confusion Matrix for Watch

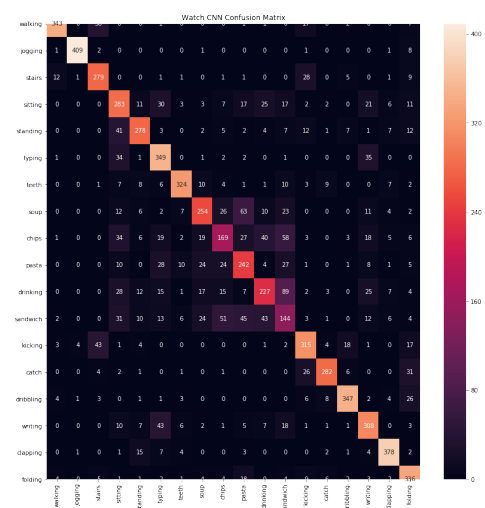


Figure 15: CNN Confusion Matrix for Watch

7 Conclusion/Future Work

Weiss (6) intends to release an updated dataset which includes significantly more participants. Additionally, the set of tasks that each participant will complete will be larger. We intend to improve upon our results going forward on the expanded WISDM dataset that will be released later. Since the expanded dataset will also include more IMUs, we will investigate using different combinations of sensors to perform our learning task.

While our best performing model improved upon Weiss' results, we believe that with further fine-tuning of hyper parameters we can continue to improve the prediction accuracy of our approach. We will experiment with using a combination of the two kinds of networks commonly known as a Convolutional Recurrent Neural Network (CRNN). It is also worth noting that we have so far only used impersonal models for our classification task, however we will investigate creating unique models for each study participant as previous research has shown this approach to be more accurate.

8 Contributions

Derek McCreight and Susana Benavidez contributed equally in the paper, experiments, and code.

References

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