

Simplifying Grocery Checkout with Deep Learning

Youtube Video Link: https://youtu.be/gEg8ZrTR0UI Jing Ning, Yongfeng Li, Ajay Ramesh {annaning, liyongfe, ajay_ramesh}@stanford.edu **Department of Computer Science, Stanford University**

INTRODUCTION

Problem Statement: Fruits and vegetables are usually not packaged in boxes. Most stores use plastic tags with identification numbers on the surface, which presents several problems.

- ◆ Unsustainable and high maintenance cost
- ♦ Not Environment-friendly
- ♦ More label-intensive for store

Goal: build a DL system that can efficiently classify and localize fruits and vegetables. We aim to apply the state-of-the-art technique Mask R-CNN.





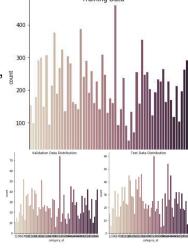
DATASET

MvTec Densely Segmented Supermarket(D2S) Dataset

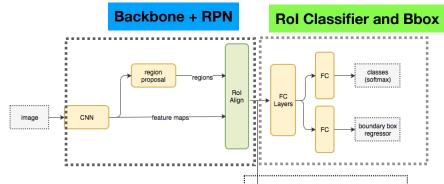
- 60 unique categories
- 1920*1440 RGB images
- Training/Dev/Test split: 2880/360/360
- Annotation format similar to COCO
- With various lighting, rotations, and backgrounds



• Class Distribution

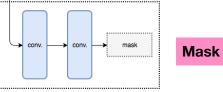


MODEL ARCHITECTURE (MASK-RCNN)



Model Pipeline

- Backbone model (Resnet-50)
- Region Proposal Network (RPN)
- Region of Interest Classification and **Bounding Box**
- Segmentation Masks



 $L = L_{cls} + L_{box} + L_{mask}$

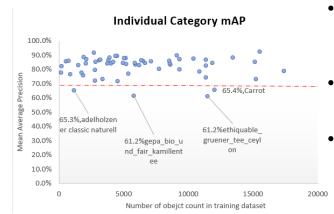
$$L_{loc}(t^u, v) = \sum_{i \in x, y, w, h} smooth_{Li}(t_i^u - v_i)$$

$$smooth_{Li}(x) = \begin{cases} 0.5x^2 & if|x| < 1\\ |x| - 0.5 & otherwise, \end{cases}$$

$$L_{mask} = -\frac{1}{m^2} \sum_{i \in i} [y_{ij} log \hat{y}_{ij}^k + (1 - y_{ij}) log (1 - \hat{y}_{ij}^k)]$$

Loss function for each Rol

ERROR ANALYSIS



- Analysis on mAP on each category and relationship between object count performed
- Carrot, Adelholzener water, and Kamillentee tee have lowest mAP
- Error appear to relate to difference in size of objects from the same category and object occlusion with limited label displaying

RESULTS

Transfer learning was applied and various of parameters were experimented. Model is initiated with COCO pre-trained weights.

Results: mAP of 84 is achieved at IoU 50:95, with tolerance to partial obstruction.

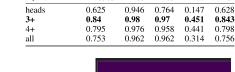
Backbone Network

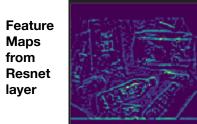
backbone	$AP_{50:95}$	AP_{50}	AP_{75}	AP_M	AP_L
ResNet-50	0.753	0.962	0.962	0.314	0.75
ResNet-101	0.788	0.957	0.924	0.291	0.79

Image Size

Image Size	$AP_{50:95}$	AP_{50}	AP_{75}	AP_M	AP_L
800*1024	0.837	0.979	0.979	0.61	0.83
512*512	0.753	0.962	0.962	0.314	0.75
256*256	0.04	0.072	0.042	0	0.05

 Number of layers to re-train





Example of model prediction result

FUTURE WORK

from

We show that Mask R-CNN can achieve state-of-art result in object instance segmentation with the right hyper-parameter tuning.

For future work, we could expand the model's application to other tasks such as fruit/vegetable sorting and quality control. To build a robustness model, increase the level of complexity of dataset, including collecting more data with images from different angles, with different background, etc.